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## THE VISIBILITY ANALYSIS PROGRAM USER'S GUIDE

PAUL KIKTA

MEDHAT KORNA

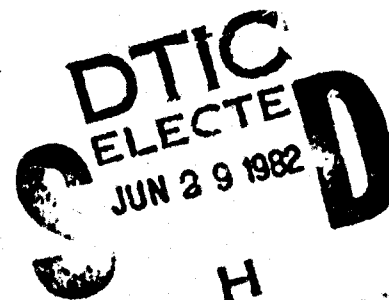
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APRIL 1982

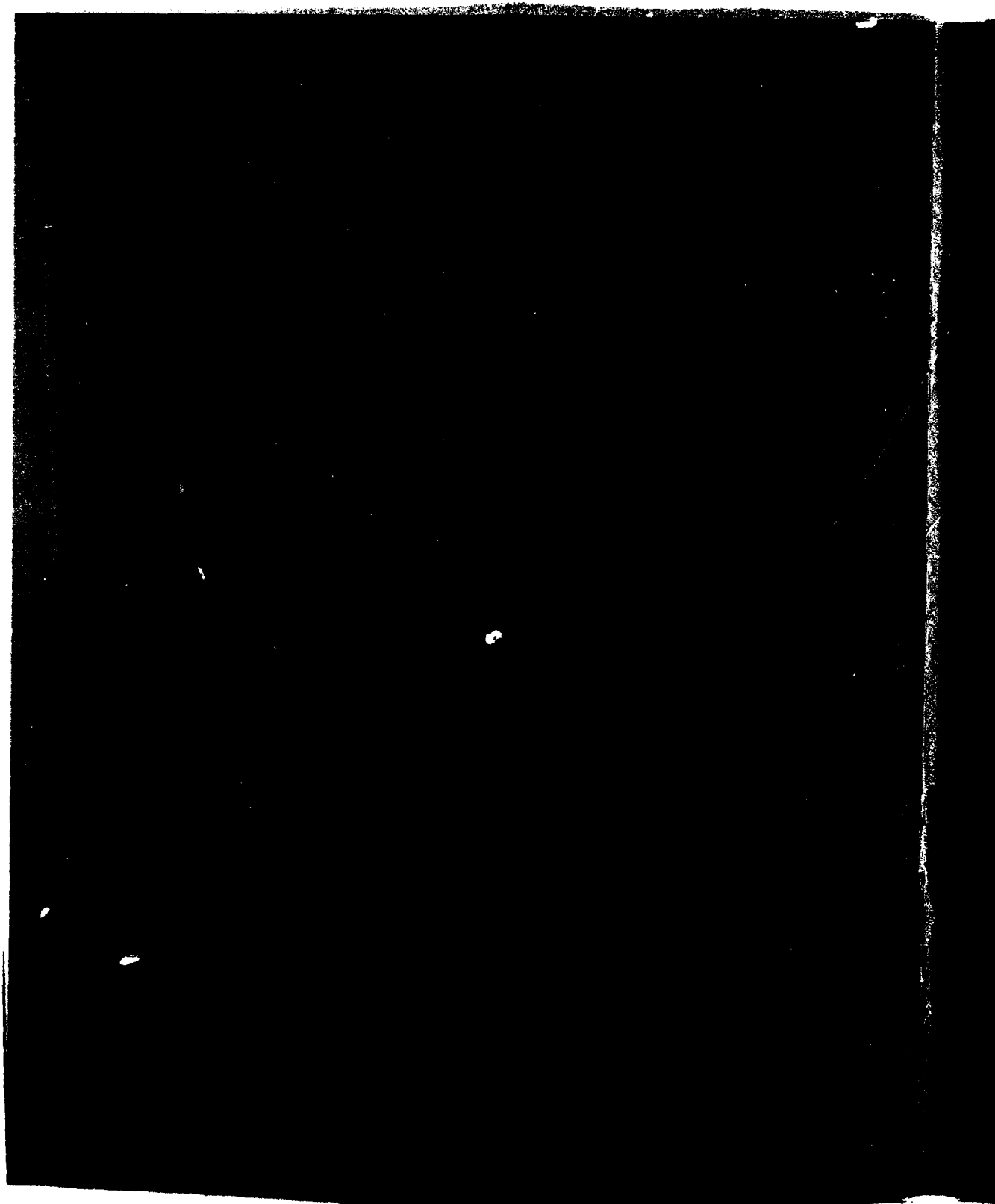


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FOR THE COMMANDER



CHARLES BATES, JR.

Chief

Human Engineering Division

Air Force Aerospace Medical Research Laboratory

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**Block 20 - Abstract (Continued)**

The Guide also describes a procedure to facilitate installation and use of the program at the user's facility. The procedure consists of three principle steps: installation of the program on user's computer system, digitization of crew stations, and program execution. A listing of the program is also included.

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## SUMMARY

Military Standard 850B titled "Aircrew Station Vision Requirements for Military Aircraft" establishes requirements for providing adequate vision from within the aircrew stations of military aircraft. The standard requires a "total vision envelope plot" as a means of demonstrating compliance. This plot is a map of visual angles of line-of-sight to obstructions to external vision, such as the aircraft structures, window frames, and accessory equipment (fixed and retractable) which obscure vision through the transparencies (windows). The standard describes a method for constructing total vision envelope plots from information found in crew station drawings. This method is quite time consuming and not versatile because plots are made from only one viewpoint, the hypothetical Design Eye Position, which is defined in MIL-STD-1333.

In developing the AFAMRL COMBIMAN (COMputerized BIomechanical MAN-model), we have created the capability to make total vision envelope plots with several enhancements not required by MIL-STD-850. Since the plots are drawn on a computer graphics device, the objects plotted need not be limited to those obstructing vision outside the aircraft, but may include the entire crew station with all the displays and controls. Because the model is general, the crew station or workplace is not limited to an aircraft cockpit, but can be any environment, such as an automobile, a computer terminal, etc. Furthermore, the model is not limited to the Design Eye Point. Plots can be quickly made from different eye positions, head orientations, or even plots from left and right eye positions.

This plotting program has such broad application that we have removed it from the COMBIMAN program so that it will be available to almost any computer user having a graphics plotter.

Dr. Joe McDaniel  
Workload and Ergonomics Branch  
Air Force Aerospace Medical  
Research Laboratory (AFAMRL)

## PREFACE

This work was performed under USAF Contract F33615-78-C-0507 entitled, *Biomechanics of Cockpit Evaluation*. The contract monitor and technical advisor for this contract is Dr. Joe McDaniel of the Workload and Ergonomics Branch of the Air Force Aerospace Medical Research Laboratory (AFAMRL), Wright-Patterson Air Force Base.

The purpose of this report is to provide a guide to use the VISIBILITY ANALYSIS program. The VISIBILITY ANALYSIS program was developed and revised over the years by the University of Dayton Research Institute as a part of the Computerized Biomechanical MAN-model (COMBIMAN) system of programs. The VISIBILITY ANALYSIS program is an independent program and runs separately from the COMBIMAN program.

Other methods of measuring cockpit visual angles include a Binocular Cockpit Visibility Camera developed between 1948 and 1951, primarily through the efforts of Mr. T. M. Edwards (1952). A comparison of 15 Air Force aircraft using this camera system was reported by Kennedy and McKechnie (1970).

The authors would like to acknowledge the contributions of Dr. Joe McDaniel, Dr. P. T. Bapu, Mr. Glen Potter and would like to thank Ms. Charlene Thompson for preparing the manuscript for publication.

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## SECTION 1

### INTRODUCTION

During the design and analysis phases of crew station development, it is essential to assess the accommodation of the crew station environment with respect to the human operator. The COMputerized BIomechanical MAN-model (COMBIMAN) system of programs has been developed to assist in the design and analysis phases of crew station development. One of the important capabilities of the COMBIMAN system of programs is to produce plots of an aircraft crew station from the crewmember's viewpoint. To enhance the capability of certain aircraft for nighttime operation, selective shieldings are installed on certain light sources. In order to evaluate these crew stations, it is necessary to map the visual angle of incidence from each crew member to each existing and proposed light source.

The VISIBILITY ANALYSIS program (VISANS) is developed to aid crew station designers to evaluate crewmembers/crew station visual interaction. The VISANS program was developed as a part of the COMBIMAN system of programs by the University of Dayton Research Institute under USAF Contract F33615-78-C-0507 entitled "Biomechanics of Cockpit Evaluation." The VISANS program is now an independent program and runs separately from the COMBIMAN program.

The VISANS program uses the three dimensional coordinates of the eye location of the crewmember and the three dimensional coordinates of the crew station (geometrically described as panels and contours) to generate a hard copy plot of the visual angles with respect to the crewmember's line-of-sight, together with legends identifying the instruments and/or light sources (see Figure 1). Four ellipses are superimposed on the plot to define the limits of various visual fields. The inner most field, denoted by the letter S, is the field of stereo vision, visible to both eyes simultaneously. The field denoted by the letter F

# VISIBILITY ANALYSIS

CREWSTATION: CH-53

CREWMEMBER'S HEAD IS POINTING 0° FROM FORWARD AND 0° FROM HORIZONTAL

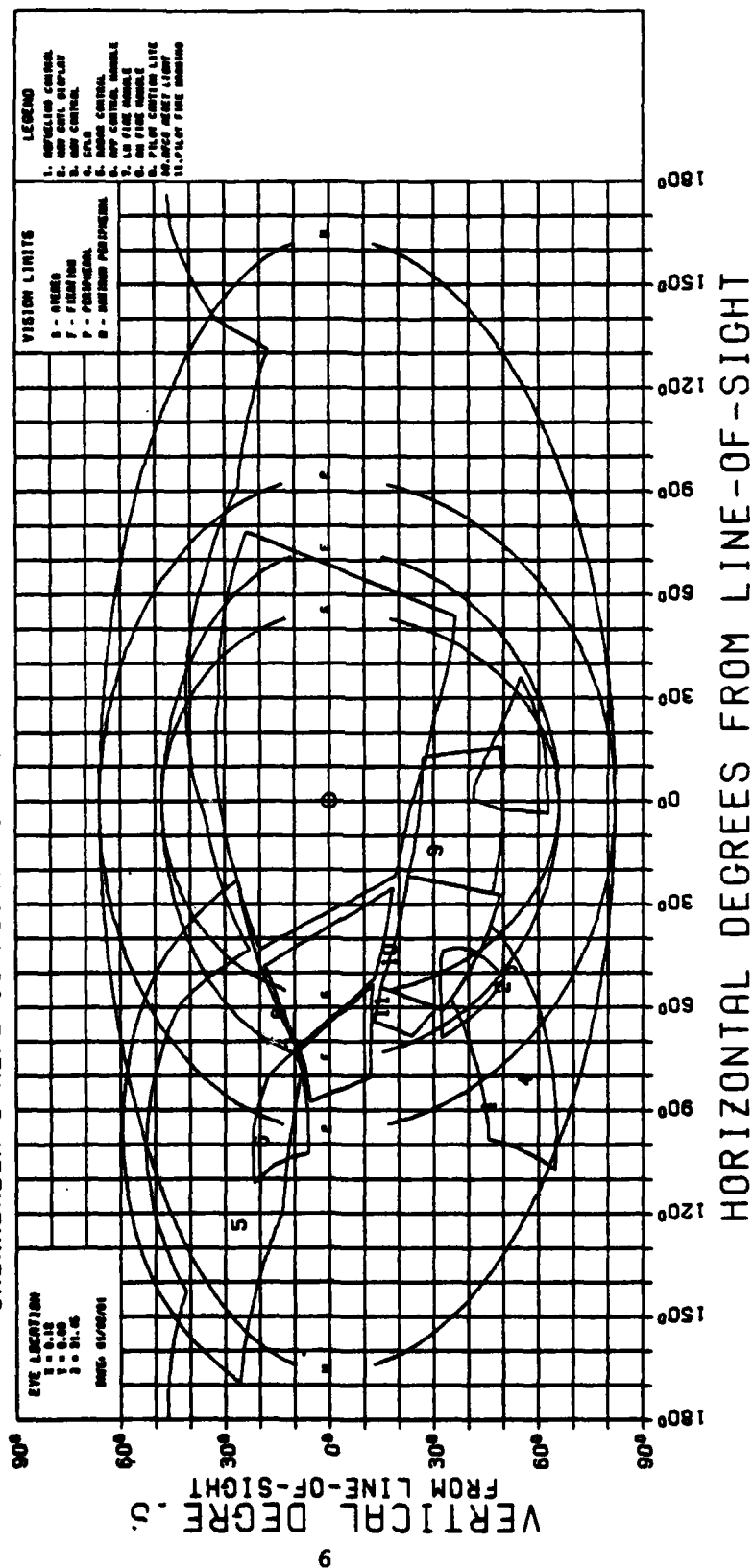


Figure 1. Example of Total Vision Envelope Plot.

is the field of fixation, that is, what the eyes can see directly without turning the head. The field denoted by the letter P is the field of peripheral vision with the eyes caged with respect to the head. The outermost field denoted by the letter M is the maximum peripheral vision limit for the extreme eye deviation. The user has the option to suppress these visual fields as explained in Section 4. In addition to generating a hard copy plot, the program calculates and prints the vision angles to each vertex of the panels and contours defining the crew station, together with the corresponding three dimensional coordinates of these vertices in the user's original coordinate system.

The panels and contours which geometrically describe the crew station may consist of 3 to 25 vertices each. These vertices must be input in consecutive order either clockwise or counterclockwise around the perimeter of each panel or contour. Miscellaneous equipment (instruments and/or light sources) consist of one vertex each, that is, a single point. Items identified with a single point location have their titles listed under the LEGEND heading as shown at the right side of the plot in Figure 1. These refer to the numbers on the plot itself. The center of the number is the exact location of the point on the plot. The coordinates of the vertices may be entered in any three dimensional system. However the user must specify the coordinates of a Seat Reference Point (SRP) with respect to the origin of the crew station coordinate system. The visibility analysis program (VISANS) converts all crew station data to a common right handed three dimensional coordinate system with the origin at the specified SRP. This conversion allows maximum flexibility for both military and nonmilitary applications.

The following procedure summary is included to facilitate installation and use of the program at the user's facility. The procedure consists of three principal steps as follows:

(1) Installation of the Program on User's Computer System.

Although the program is written in FORTRAN IV, the conventions for end-of-file (EOF) detection, plot initialization and termination,

as well as file handling procedures may differ from system to system and some minor modifications may be needed. In addition, the JCL and device references of Section 5 describe the procedures for a particular set of hardware and operating system (specifically a CDC 6600 computer, CDC tape drives, CALCOMP plotting hardware, and a NOS/BE operating system). It will be necessary to tailor the job control language to the user's system. A listing of the program is included in Appendix B.

(2) Digitization of Crew Stations. The workplace or crew station must be reduced to points, lines, and panels as described in Section 2 and Paragraph 4.2. These data may be stored on punched cards, magnetic tape, or disk, but must be coded for the user's specific application prior to using the program. The contents and complexity of these data depends on the user's application. In the examples in this report only the major console and window outlines are depicted along with a few control references; however, individual control panels, knobs, dials, etc., may be included if the user requires them.

(3) Program Execution. Each program run requires crew station data, an eye location, and eye orientation information. These requirements are described in detail in Paragraph 4.2. Note that it is possible to obtain many plots in a single run, each depicting a different crew station and/or eye orientation, by judicious arrangement of the input data.

## SECTION 2

### AN ILLUSTRATION

In order to use the Visibility Analysis Program (VISANS) the user must be able to geometrically describe the crew station to be analyzed. The example used to illustrate this procedure is based on the crew station in Figure 2 consisting of a six drawer desk. In modeling the desk, only the desk's top, front side, and leg well are defined. The other sides are not needed because they do not cause any physical or visual interference to a person sitting at a desk.

First, we arbitrarily choose an origin and define a coordinate system. In this example we chose the mid-point of the front edge of the top of the desk to be the origin and defined the coordinate system as follows:

+X Forward  
+Y Left  
+Z Up .

Using the dimensions of the desk, and the origin of the coordinate system, the three dimensional coordinates are obtained for the various vertices of the panels and for the location of any controls or other miscellaneous equipment as needed. Next the user must supply the program with the three dimensional coordinates of the Seat Reference Point (SRP) with respect to the origin of the crew station's coordinate system. The three dimensional coordinates of SRP with respect to the origin of the desk are defined as follows:

X-Coordinate = -15.0  
Y-Coordinate = 0.0  
Z-Coordinate = -11.0 .

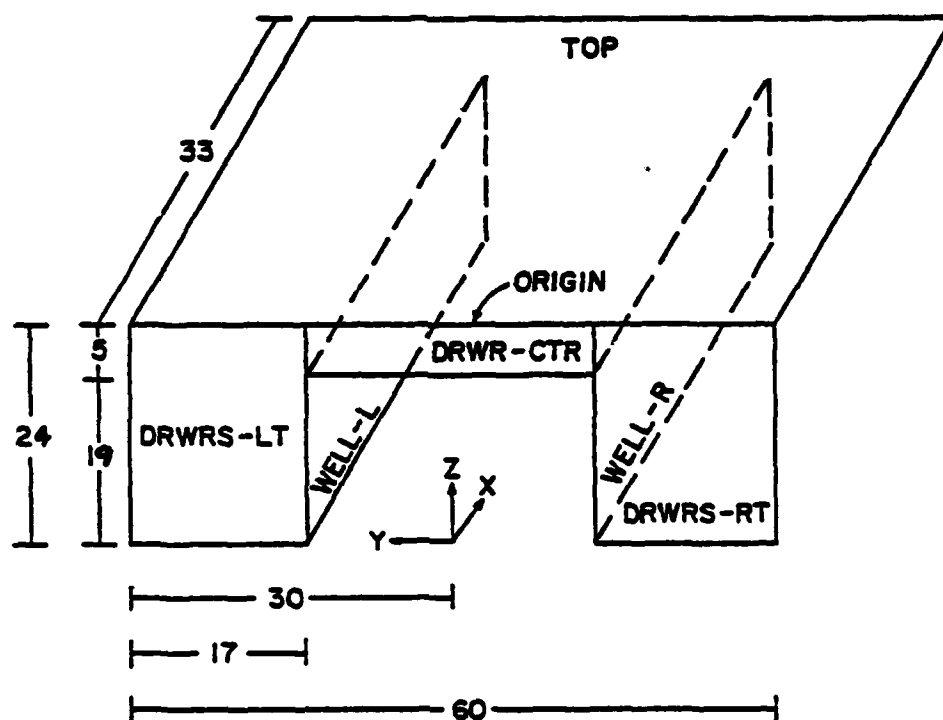


Figure 2. Sample Crew Station - DESK.

As shown in Figure 2, the "DESK" consists of a total of six panels. Each panel has four vertices, and is rectangular in shape. The coordinates of the vertices are shown in Figures 3a and 3b.

Figure 4a shows a visibility plot of the "DESK" shown in Figure 2. The eye location ( $X=6.12$ ,  $Y=0.0$ , and  $Z=31.46$ ) shown in this figure was arbitrarily selected, the user may enter any desired values as described in Paragraph 4.1. The user may modify or change the visual field overlays by changing the equations defining these overlays in subroutine VISPLT (see Appendix B). For this example, the crewmember (the person sitting at the desk) is looking  $0^\circ$  from forward and  $0^\circ$  from horizontal. The information provided by the visibility plot is explained in Paragraph 3.1.

Figure 4b shows the program input used to generate the visibility plot. This is explained in Section 4.





# ITOP

POINT	X	Y	Z
1	0.0	30.0	0.0
2	33.0	30.0	0.0
3	33.0	-30.0	0.0
4	0.0	-30.0	0.0



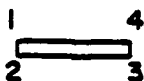
# 2DRWRS - LT

POINT	X	Y	Z
1	0.0	30.0	0.0
2	0.0	13.0	0.0
3	0.0	13.0	-24.0
4	0.0	30.0	-24.0



# 3DRWRS - RT

POINT	X	Y	Z
1	0.0	-30.0	0.0
2	0.0	-13.0	0.0
3	0.0	-13.0	-24.0
4	0.0	-30.0	-24.0



# 4DRWRS - CT

POINT	X	Y	Z
1	0.0	13.0	0.0
2	0.0	13.0	-5.0
3	0.0	-13.0	-5.0
4	0.0	-13.0	0.0

Figure 3a. X, Y, and Z Coordinates of Panels of DESK.

1	4
2	3

# 5WELL-LT

<u>POINT</u>	<u>X</u>	<u>Y</u>	<u>Z</u>
1	0.0	13.0	-5.0
2	0.0	13.0	-24.0
3	33.0	13.0	-24.0
4	33.0	13.0	-5.0

1	4
2	3

# 6WELL-RT

<u>POINT</u>	<u>X</u>	<u>Y</u>	<u>Z</u>
1	0.0	-13.0	-5.0
2	0.0	-13.0	-24.0
3	33.0	-13.0	-24.0
4	33.0	-13.0	-5.0

Figure 3b. X, Y, and Z Coordinates of Panels of DESK.

# VISIBILITY ANALYSIS

CREWSTATION: DESK

CREWMEMBER'S HEAD IS POINTING 0° FROM FORWARD AND 0° FROM HORIZONTAL

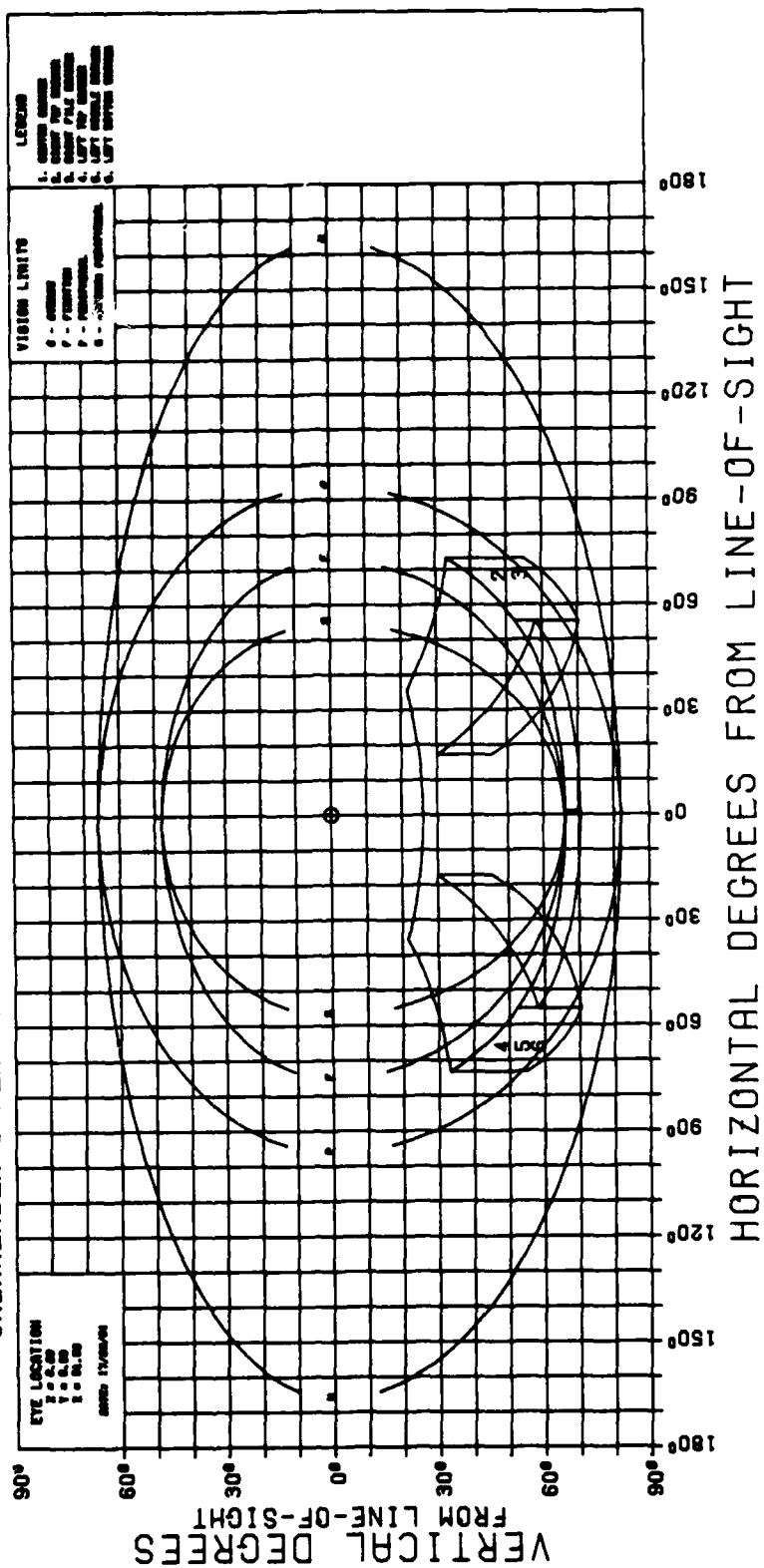


Figure 4a. Visibility Plot of the "DESK".

15

**Figure 4b. Input Data Generating the Visibility Plot in Figure 4a.**

SECTION 3  
THE VISIBILITY ANALYSIS (VISANS) PROGRAM\* OUTPUT

This program provides visibility data to evaluate crewmember/crew station or other crew station interactions. It allows the user to label the instruments and/or light sources (miscellaneous equipments) of a crew station and it also includes an optional overlay defining the limits of various visual fields.

3.1 THE VISIBILITY ANALYSIS OUTPUT

The program provides both printed and graphical output (hard copy plot). The graphical output is shown in Figure 4c. The plot provides the user with the following information:

- (1) The eye location of the crewmember with respect to the seat reference point (SRP) of the crew station (see Paragraph 4.2).
- (2) The name of the crew station.
- (3) Definition of the vision limits.
- (4) The vision limits themselves.
- (5) A rectilinear plot of the crew station and miscellaneous equipments.
- (6) A LEGEND defining the miscellaneous equipment.
- (7) The orientation of the head, in degrees.\*

The printed output for this program contains:

- (1) An output from subroutine VISVDM containing the crew station data (Figure 5 is an example of subroutine VISVDM output - see Paragraph 4.2 for details), and
- (2) An output from the main routine for each plot consisting of the Namelist CNTRL's variable values, the eye location, head orientation, and, for each vertex, its three dimensional coordinates (in the original crew station coordinate system) along with the vision angles at which that vertex can be found.

\*Note that for line-of-sight angles, positive horizontal is left of forward and positive vertical is above the horizontal.

# VISIBILITY ANALYSIS

CREWMEMBER'S HEAD IS POINTING 10° LEFT OF FORWARD AND 30° BELOW HORIZONTAL

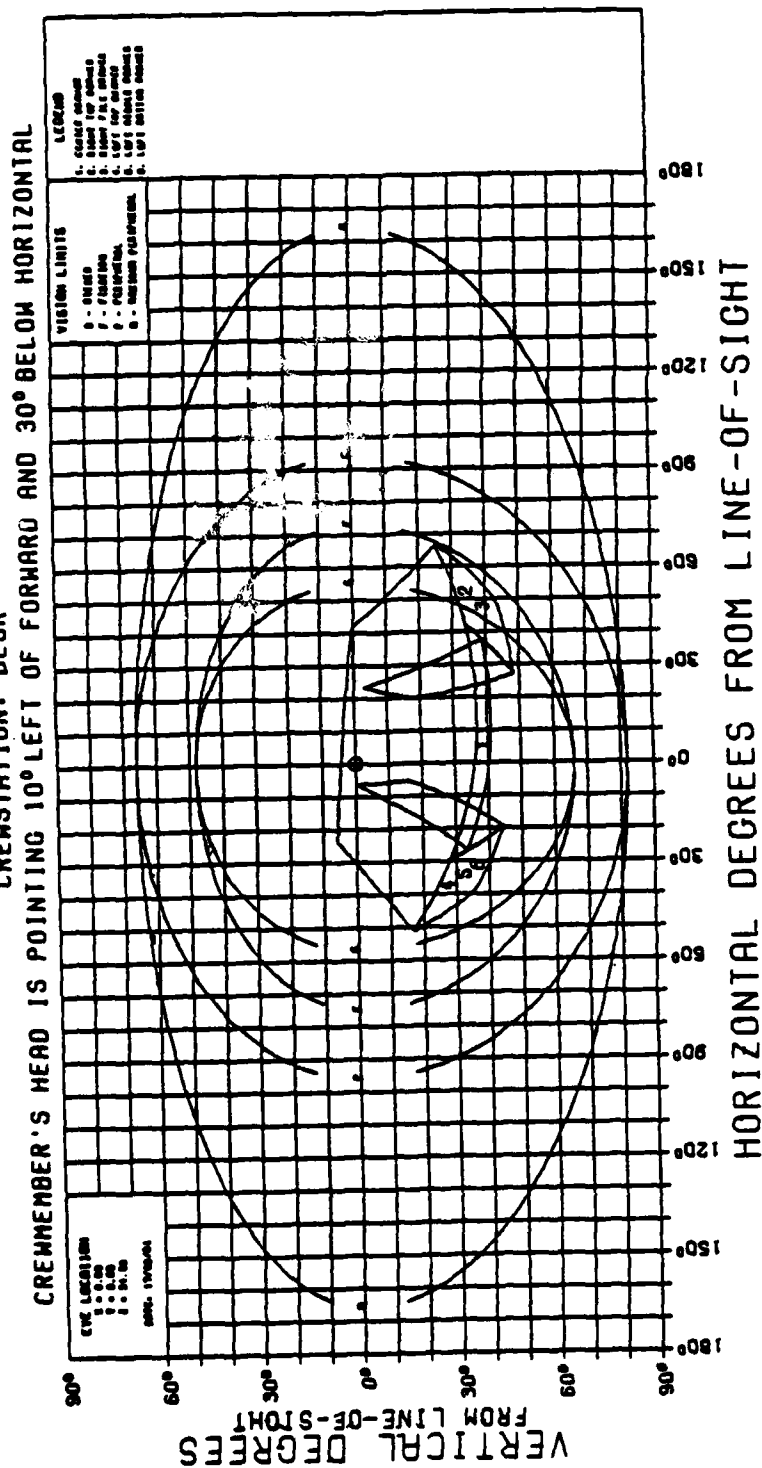


Figure 4c. The Graphical Output of the Desk. (The person sitting at the desk is look 30° down and 10° to the left.)

```

VIS5001 GADD CM 53 121113.00 24.00148.70 A R U
VIS5191 MEMBER, CM-13 (01/02/01), HAS 12 BOUNDARIES AND 11 MISCELLANEOUS EQUIPMENTS
VIS5201 COORDINATES ARE TRANSLATED TO ( 143.00, 24.00, 140.70).
VIS5211 COORDINATES GIVEN AS A, R AND U ARE NOW F, L, AND U.
1.) RSIDE
4 VERTICES --INPUT COORDINATES--
( 116.25 13.21 146.73) TO ( 27.55 10.75 6.03) --ABSOLUTE COORDINATES--
( 116.25 30.00 146.73) TO ( 27.55 -6.00 6.03)
( 111.47 30.00 158.55) TO ( 32.33 -6.00 17.05)
( 110.01 13.21 160.14) TO ( 32.99 10.75 19.44)
2.) CENTER
4 VERTICES --INPUT COORDINATES--
( 116.01 13.21 145.07) TO ( 26.99 10.75 4.37)
( 110.01 13.21 160.14) TO ( 32.99 10.75 19.44)
( 110.01 -13.21 160.14) TO ( 32.99 37.25 19.44)
( 116.01 -13.21 145.07) TO ( 26.99 37.25 4.37)
3.) LSIDE
4 VERTICES --INPUT COORDINATES--
( 116.25 -13.21 146.73) TO ( 27.55 37.25 6.03)
( 110.01 -13.21 160.14) TO ( 32.99 37.25 19.44)
( 111.47 -30.00 158.55) TO ( 32.33 54.00 17.05)
( 116.25 -30.00 146.73) TO ( 27.55 54.00 6.03)
4.) OVERHEAD
4 VERTICES --INPUT COORDINATES--
( 126.92 19.44 178.00) TO ( 16.00 4.56 37.30)
( 162.00 19.44 184.00) TO ( -10.20 4.56 43.30)
( 162.00 -19.44 184.00) TO ( -10.20 43.44 43.30)
( 126.92 -19.44 178.00) TO ( 16.00 43.44 37.30)
5.) LWRCONSL
4 VERTICES --INPUT COORDINATES--
( 142.30 8.75 138.22) TO ( 1.42 15.25 -2.48)
( 116.01 8.75 145.07) TO ( 26.99 15.25 4.37)
( 116.01 -8.75 145.07) TO ( 26.99 32.75 4.37)
( 142.30 -8.75 138.22) TO ( 1.42 32.75 -2.48)
50.) WINDOW-UPPER RIGHT
10 VERTICES --INPUT COORDINATES--
( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
( 131.00 13.00 184.00) TO ( 12.00 11.00 43.30)
( 140.00 13.00 187.00) TO ( 3.00 11.00 46.30)
( 152.00 13.00 188.00) TO ( -8.20 11.00 47.30)
( 152.00 27.00 187.00) TO ( -8.20 -3.00 46.30)
( 152.00 36.10 184.00) TO ( -8.20 -12.10 43.30)
( 136.00 30.00 179.00) TO ( -8.20 -16.30 38.30)
( 134.00 33.00 179.00) TO ( 9.00 -14.00 30.30)
( 126.00 23.00 179.00) TO ( 9.00 -9.00 38.30)
( 126.00 -13.00 179.00) TO ( 19.00 1.00 38.30) --ABSOLUTE COORDINATES--
( 131.00 13.00 184.00) TO ( 17.00 37.00 38.30)
( 140.00 13.00 187.00) TO ( 12.00 37.00 43.30)
( 152.00 13.00 188.00) TO ( 3.00 37.00 46.30)
( 152.00 -13.00 188.00) TO ( -8.20 37.00 47.30)
( 152.00 -27.00 187.00) TO ( -8.20 51.00 46.30)
( 152.00 36.10 184.00) TO ( 8.20 60.10 43.30)
( 152.00 -40.30 179.00) TO ( -8.20 64.30 38.30)
( 136.00 -30.00 179.00) TO ( 5.00 62.00 38.30)
57.) WINDOW-UPPER LEFT
10 VERTICES --INPUT COORDINATES--
( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
( 131.00 13.00 184.00) TO ( 12.00 11.00 43.30)
( 140.00 13.00 187.00) TO ( 3.00 11.00 46.30)
( 152.00 13.00 188.00) TO ( -8.20 11.00 47.30)
( 152.00 27.00 187.00) TO ( -8.20 -3.00 46.30)
( 152.00 36.10 184.00) TO ( -8.20 -12.10 43.30)
( 136.00 30.00 179.00) TO ( -8.20 -16.30 38.30)
( 134.00 33.00 179.00) TO ( 9.00 -14.00 30.30)
( 126.00 23.00 179.00) TO ( 9.00 -9.00 38.30)
( 126.00 -13.00 179.00) TO ( 19.00 1.00 38.30) --ABSOLUTE COORDINATES--
( 131.00 13.00 184.00) TO ( 17.00 37.00 38.30)
( 140.00 13.00 187.00) TO ( 12.00 37.00 43.30)
( 152.00 13.00 188.00) TO ( 3.00 37.00 46.30)
( 152.00 -13.00 188.00) TO ( -8.20 37.00 47.30)
( 152.00 -27.00 187.00) TO ( -8.20 51.00 46.30)
( 152.00 36.10 184.00) TO ( 8.20 60.10 43.30)
( 152.00 -40.30 179.00) TO ( -8.20 64.30 38.30)
( 136.00 -30.00 179.00) TO ( 5.00 62.00 38.30)

```

Figure 5. Subroutine VISVDM Printed Output.





```

11 ) REFUELLING CONTROL      ( 105.10 -30.50 110.70) TO ( 36.70 62.50 -30.00)
( 103.30 35.00 106.30) TO ( 40.50 59.00 -34.40)
( 101.80 -20.30 102.90) TO ( 42.00 52.30 -37.80)
( 101.50 -21.00 102.10) TO ( 42.30 49.00 -30.60)
( 93.20 -21.00 100.60) TO ( 50.00 45.00 -32.10)
( 88.60 -21.00 115.30) TO ( 55.20 45.00 -25.40)
( 86.50 -23.40 122.00) TO ( 57.30 47.40 18.70)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 137.50 -6.00 139.50) TO ( 6.30 30.00 -1.20)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 124.50 5.00 143.00) TO ( 19.30 19.00 2.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 124.00 7.50 143.25) TO ( 19.00 16.50 2.55)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 135.00 4.00 140.00) TO ( 8.00 20.00 -.70)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 150.00 6.00 162.00) TO ( 6.20 18.00 41.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 142.00 0.00 160.00) TO ( 1.00 24.00 39.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 128.00 -5.00 177.00) TO ( 15.00 29.00 36.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 128.00 5.00 177.00) TO ( 15.00 19.00 36.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 116.00 18.00 150.00) TO ( 27.00 6.00 17.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 116.00 0.00 161.00) TO ( 27.00 24.00 20.30)
1 VERTICES --INPUT COORDINATES-- --ABSOLUTE COORDINATES--
( 116.00 -10.00 150.00) TO ( 27.00 42.00 17.30)
WTS9361 CH-53 WITH 12 BOUNDARIES AND 11 MISCELLANEOUS EQUIPMENTS HAS BEEN ADDED.

```

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Figure 5. Subroutine VISVDM Printed Output.

Figure 6 is a sample of the main routine output and contains the following:

- (1) The program name.
- (2) The page number.
- (3) The visibility member name and the date created.
- (4) The eye location.
- (5) The head orientation.
- (6) Each visibility contour, panel, and/or point source name.
- (7) Cross reference output showing the vision angles for each vertex of the visibility member.

VISIBILITY MEMBER NAME CH-53 (01702/81)  
EYE LOCATION IN SRP SYSTEM ( 6.12, 0.00, 31.45)  
LINE-OF-SIGHT IN DEGREES ( 0, 0)

VISIBILITY PLOT DATA FOR: KSIDE  
ORIGINAL COORDINATES  
A R U

LINE-OF-SIGHT ANGLES  
HORIZ. VERT.  
27 -47  
-16 -49  
-13 -27  
22 -23

116.250 13.250 146.730  
116.250 30.000 146.730  
111.470 30.000 158.550  
110.810 13.250 160.140

VISIBILITY PLOT DATA FOR: CENTER

LINE-OF-SIGHT ANGLES  
HORIZ. VERT.  
27 -49  
22 -23  
54 -15  
61 -32

116.810 13.250 145.070  
110.810 13.250 160.140  
110.810 -13.250 160.140  
116.810 -13.250 145.070

VISIBILITY PLOT DATA FOR: LSIDE

LINE-OF-SIGHT ANGLES  
HORIZ. VERT.  
60 -31  
54 -15  
64 -13  
68 -24

116.250 -13.250 146.730  
110.810 -13.250 160.140  
111.470 -30.000 158.550  
116.250 -30.000 146.730

VISIBILITY PLOT DATA FOR: OVERHEAD

LINE-OF-SIGHT ANGLES  
HORIZ. VERT.  
23 27  
169 26  
119 13  
74 7

126.920 19.440 178.000  
162.000 19.440 164.000  
162.000 19.440 164.000  
126.920 -19.440 178.000

Figure 6. Sample of Main Routine Printed Output. For line-of-sight angles, positive horizontal is left of forward, positive vertical is above the horizontal.

## SECTION 4

### INPUT TO VISANS PROGRAM

The input for program VISANS is of three types:

- (1) input/output control,
- (2) crew station data, and
- (2) eye/head positional data.

The data stream is entered in the following form:

- the namelist CNTRL,
- crew station data,
- coordinates of the eye position, and
- coordinates of the point at which the head is pointing or the vertical and horizontal angular offsets of the head with respect to straightforward.

As many sets of input as desired may be entered ending with:

- the namelist CNTRL with IEND=1.

The general deck layout is shown in Figure 7. The following three paragraphs describe the format and content of the data input.

#### 4.1 THE NAMELIST CNTRL

Input/output control for VISANS is accomplished using the namelist CNTRL. The namelist CNTRL and its default values are:

- NEW - if NEW is set equal to 1, VISVDM is called to read crew station data from Unit 3\* in card image format as described in Paragraph 4.2 (default:0). If NEW=0, VISVDM is bypassed and the data is read from Unit 9.\*\* (This is the case after the first plot when more than one plot of the same crew station are requested).

---

\*Unit 3 is defined by the user and contains the input data.

\*\*Unit 9 is where the reformatted data is written for use by program.

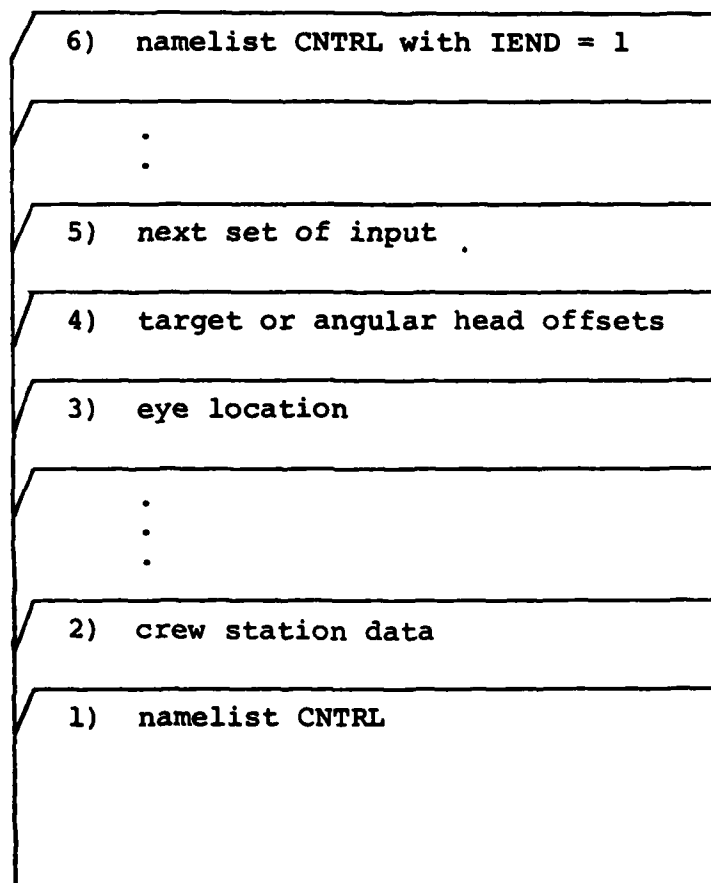


Figure 7. General Input Deck Layout.

- EYELOC - if EYELOC is set equal to 1, the eye location is read from Unit 3\*, otherwise the EYELOC used on the previous plot is used. If this is the first plot and EYELOC=0, the Design Eye Position (described in MIL-STD-1333) for a 13° seat back angle (6.07, 0.0, 31.5) is used (default:0).
- TARG - if TARG is set equal to zero, horizontal and vertical angle offsets for the line-of-sight are read from UNIT 3. If TARG=1, the program looks for the three dimensional coordinates of the point at which the eye is looking. (The coordinates are read from Unit 3.\*) (default:0).
- ILIM - if ILIM is set equal to 1, the vision limits are superimposed on the visibility plot. If ILIM=0, no vision limits are plotted. (default:1).
- IEND - IEND set equal to 1 denotes the end of the input data. If IEND=0, the program looks for more data on Unit 3. (default:0).

The format of the namelist CNTRL is as follows (see Figure 8a):

- column 1        a blank
- column 2        a dollar sign(\$)\*\*
- column 3-7     the word CNTRL
- column 8        a blank.

After column 8 the user may code none, all or any combinations of the control variables in the form NEW=1, EYELOC=1, ..., the last one followed by a \$ sign. Note that, although embedded blanks are acceptable, on some machines they will be considered as zeros when they occur between a variable value and the following comma. Thus, a namelist string of the form NEW=1, EYELOC=1, IEND=1\$ might be interpreted as NEW=1, EYELOC=10, and IEND=1.

---

\*Unit 3 is defined by the user and contains the input data.

\*\*Note that the format of the Namelist convention is highly machine dependent.



Figure 8b is the namelist CNTRL input that contributed to Figure 2 as follows:

- NEW=1 caused VISVDM to be called to read the CH-53 data from Unit 3.
- EYELØC=1 therefore, eye location was read as X=6.12, Y=0.0, Z=31.45.
- TARG=0 therefore, the vertical and horizontal angle offsets were read as VANG=0° and HANG=0°, i.e. head is pointing straightforward.
- ILIM=1 therefore, the vision limits are overlayed onto the visibility plot.
- IEND=0 indicating that this is not the end of the input data.

#### 4.2 ENTERING CREW STATION DATA

Crew station data are entered with coordinates in a user defined coordinate system (see Section 2). Data may be entered as boundary definitions (panels or visibility contours) consisting of three to twenty-five vertices, or single point miscellaneous equipment to be labeled and identified on the plot legend. A combined total of 100 boundary definitions and miscellaneous equipment is allowed with no more than 40 miscellaneous equipment. The data flow is shown in Figure 9.

##### (1) The \$ADD card containing

columns 1-4	\$ADD
column 5	blank
columns 6-13	crew station member name
columns 14-16	the number of visibility boundary definitions for this member (NBNDs)
columns 17-18	the number of miscellaneous equipment for this member (NEQPTS)
columns 19-24	the neutral seat reference point (NSRP)
	X-coordinate (ACXYZ(1))*
columns 25-30	the NSRP Y-coordinate (ACXYZ(2))*
columns 31-36	the NSRP Z-coordinate (ACXYZ(3))*
column 37	blank

\*Note that the coordinates of the NSRP are in the user's defined coordinate system.





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column	38	the direction of the positive x-axis of the input coordinate system (IX), with respect to the operator, as follows:
		F for Forward
		A for Aft
		L for Left
		R for Right
		U for Up
		D for Down
column	39	blank
column	40	the direction of the positive y-axis defined as above (IY)
column	41	blank
column	42	the direction of the positive z-axis defined as above (IZ)

(2) The NBNDS boundary definitions as follows:

Card 1 columns	1-3	sequence number for this boundary (BNØ)
columns	4-27	the boundary name (BNAME)
columns	28-29	blank
columns	30-32	the number of vertices for this boundary (BNV)

This is followed by BNV cards with the coordinates for each vertex as follows:

columns	1-6	the X-coordinate in the input coordinate system*
columns	7-12	the Y-coordinate for this vertex
columns	13-18	the Z-coordinate for this vertex

(3) The NEQPTS miscellaneous equipment definitions as follows:

Card 1 columns	1-3	a sequence number (BNØ)
columns	4-27	the name for this point to be placed in the legend (BNAME)
column	32	a 1
Card 2 columns	1-6	the X-coordinate for this point in the input coordinate system
columns	7-12	the Y-coordinate for this point
columns	13-18	the Z-coordinate for this point

\*Note that if a decimal point is not included for any coordinate, one is assumed to be between the second last and third to the last columns of each field (F6.2).

Figure 10 shows input for the Air Force's PAVLØ aircraft which contributed to the plot in Figure 1. Figure 11 shows the printed output generated by VISVDM. The first line shows the \$ADD card as read by the program.

```
$ADD CH-53 121143.8 524143.80 24.00140.70 A R U
```

The second output line gives the member name, creation date, number of boundaries, and number of miscellaneous equipment, as read from the \$ADD card.

```
MEMBER,CH-53 PAVLO (01/02/81), HAS 12 BOUNDARIES AND 11 MISCELLANEOUS EQUIPMENT
```

The third line shows the X, Y, and Z coordinate offsets used to translate the new station to the programs coordinate system with the origin at the NSRP.

```
COORDINATES ARE TRANSLATED TO (143.80, 24.00, 140.70).
```

The next line describes the direction changes in the coordinate system as follows:

```
COORDINATES GIVEN AS A, R AND U ARE NOW F, L, AND U.
```

<u>Input</u>	<u>Absolute</u>
+ x - <u>A</u> ft (Fuselage Station)	+ x - <u>F</u> orward
+ y - <u>R</u> ight (Butt Line)	+ y - <u>L</u> eft
+ z - <u>U</u> p (Waterline)	+ z - <u>U</u> p

The remaining VISVDM printed output includes, for each boundary and miscellaneous equipment, the sequence number, the number of vertices, and the coordinates of each vertex both before and after translation. The last line starting with VIS534I is a message which indicates that VISVDM has successfully completed processing the visibility member.

SCNTRL NEW=1 3		
LA00 CH-53	12111 3.8 24.0 140.7 A R U	01/02/81
1KSIDE	1 4	
116.25 13.25146.73		
116.25 30.00146.73		
111.47 30.00158.55		
110.81 13.25160.14		
2CENTER	1 4	
116.81 13.25145.07		
110.81 13.25160.14		
110.81-13.25160.14		
116.81-13.25145.07		
3LSIDE	1 4	
116.25-13.25146.73		
110.81-13.25160.14		
111.47-30.00158.55		
116.25-30.00146.73		
4OVERHEAD	1 4	
126.92 19.4+178.00		
152.00 19.4+184.00		
162.00-19.4+184.00		
125.92-19.4+178.00		
5LWRCONSL	1 4	
1-2.38 8.75138.22		
116.81 8.75145.07		
116.81 -8.75145.07		
1-2.38 -8.75138.22		
11REFUELING CONTROL	8 1	
137.50 -6.00139.50		
16NAV CNTL DISPLAY	8 1	
124.50 5.00143.00		
17NAV CONTROL	8 1	
124.00 7.50143.25		
28CPLR	8 1	
135.00 4.00140.00		
21RADAR CONTROL	8 1	
150.00 6.00182.00		
22APP CONTROL HANDLE	8 1	
142.00 0.0 180.00		
23LM FIRE HANDLE	8 1	
128.00 -5.00177.00		
24RH FIRE HANDLE	8 1	
128.00 5.00177.00		
29PILOT CAUTION LITE	8 1	
116.00 18.00158.00		
30AFCS RESET LIGHT	8 1	
116.00 0.0 161.00		
31PILOT FIRE WARNING	8 1	
116.00-18.00158.00		
6.12	31 45	
SCNTRL IENO=1 3		

Boundary  
Data

Miscellaneous  
Equipments

Figure 10. CH-53 Aircraft Input.

```

VIS5001 SADD CH 53      12111+3.00 24.00140.70 A R U
VIS5191 MEMBER, CH-53   (01/02/81), HAS 12 BOUNDARIES AND 11 MISCELLANEOUS EQUIPMENTS
VIS5201 COORDINATES ARE TRANSLATED TO ( 143.00, 24.00, 140.70).
VIS5211 COORDINATES GIVEN AS A, R AND U ARE NOW F, L, AND U.

1.) RSIDE
  4 VERTICES --INPUT COORDINATES--
    ( 116.25 13.25 146.73) TO ( 27.55 10.75 6.03)
    ( 116.25 30.00 146.73) TO ( 27.55 10.75 6.03)
    ( 111.47 30.00 150.55) TO ( 32.33 10.75 6.03)
    ( 118.01 13.25 160.14) TO ( 32.99 10.75 19.44)
  --ABSOLUTE COORDINATES--
  4 VERTICES --INPUT COORDINATES--
    ( 116.01 13.25 145.07) TO ( 26.99 10.75 4.37)
    ( 118.01 13.25 160.14) TO ( 32.99 10.75 19.44)
    ( 118.01 13.25 160.14) TO ( 32.99 10.75 19.44)
    ( 116.01 13.25 145.07) TO ( 26.99 10.75 4.37)
  --ABSOLUTE COORDINATES--
  4 VERTICES --INPUT COORDINATES--
    ( 116.25 13.25 146.73) TO ( 27.55 10.75 6.03)
    ( 118.01 13.25 160.14) TO ( 32.99 10.75 19.44)
    ( 111.47 30.00 150.55) TO ( 32.33 10.75 6.03)
    ( 116.25 30.00 146.73) TO ( 27.55 10.75 6.03)
  --ABSOLUTE COORDINATES--
  4 VERTICES --INPUT COORDINATES--
    ( 126.92 19.44 178.00) TO ( 16.00 4.56 37.30)
    ( 162.00 19.44 164.00) TO ( 18.20 4.56 43.30)
    ( 162.00 19.44 164.00) TO ( 18.20 4.56 43.30)
    ( 126.92 19.44 178.00) TO ( 16.00 4.56 37.30)
  --ABSOLUTE COORDINATES--
  4 VERTICES --INPUT COORDINATES--
    ( 142.30 8.75 130.22) TO ( 1.42 15.25 2.40)
    ( 116.01 8.75 145.07) TO ( 26.99 15.25 4.37)
    ( 116.01 8.75 145.07) TO ( 26.99 15.25 4.37)
    ( 142.30 8.75 130.22) TO ( 1.42 15.25 2.40)
  --ABSOLUTE COORDINATES--
  10 VERTICES --INPUT COORDINATES--
    ( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
    ( 131.00 13.00 164.00) TO ( 12.00 11.00 43.30)
    ( 140.00 13.00 167.00) TO ( 3.00 11.00 46.30)
    ( 152.00 13.00 180.00) TO ( 8.20 11.00 47.30)
    ( 152.00 27.00 187.00) TO ( 8.20 11.00 47.30)
    ( 152.00 36.10 184.00) TO ( 8.20 12.10 43.30)
    ( 152.00 40.30 179.00) TO ( 8.20 16.30 30.30)
    ( 136.00 30.00 179.00) TO ( 5.00 14.00 30.30)
    ( 134.00 33.00 179.00) TO ( 9.00 9.00 30.30)
    ( 126.00 23.00 179.00) TO ( 15.00 1.00 30.30)
  --ABSOLUTE COORDINATES--
  10 VERTICES --INPUT COORDINATES--
    ( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
    ( 131.00 13.00 164.00) TO ( 12.00 11.00 43.30)
    ( 140.00 13.00 167.00) TO ( 3.00 11.00 46.30)
    ( 152.00 13.00 180.00) TO ( 8.20 11.00 47.30)
    ( 152.00 27.00 187.00) TO ( 8.20 11.00 47.30)
    ( 152.00 36.10 184.00) TO ( 8.20 12.10 43.30)
    ( 152.00 40.30 179.00) TO ( 8.20 16.30 30.30)
    ( 136.00 30.00 179.00) TO ( 5.00 14.00 30.30)
    ( 134.00 33.00 179.00) TO ( 9.00 9.00 30.30)
    ( 126.00 23.00 179.00) TO ( 15.00 1.00 30.30)
  --ABSOLUTE COORDINATES--
  37.) WINDOW-UPPER LEFT
    ( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
    ( 131.00 13.00 164.00) TO ( 12.00 11.00 43.30)
    ( 140.00 13.00 167.00) TO ( 3.00 11.00 46.30)
    ( 152.00 13.00 180.00) TO ( 8.20 11.00 47.30)
    ( 152.00 27.00 187.00) TO ( 8.20 11.00 47.30)
    ( 152.00 36.10 184.00) TO ( 8.20 12.10 43.30)
    ( 152.00 40.30 179.00) TO ( 8.20 16.30 30.30)
    ( 136.00 30.00 179.00) TO ( 5.00 14.00 30.30)
    ( 134.00 33.00 179.00) TO ( 9.00 9.00 30.30)
    ( 126.00 23.00 179.00) TO ( 15.00 1.00 30.30)
  --ABSOLUTE COORDINATES--
  37.) WINDOW-UPPER RIGHT
    ( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
    ( 131.00 13.00 164.00) TO ( 12.00 11.00 43.30)
    ( 140.00 13.00 167.00) TO ( 3.00 11.00 46.30)
    ( 152.00 13.00 180.00) TO ( 8.20 11.00 47.30)
    ( 152.00 27.00 187.00) TO ( 8.20 11.00 47.30)
    ( 152.00 36.10 184.00) TO ( 8.20 12.10 43.30)
    ( 152.00 40.30 179.00) TO ( 8.20 16.30 30.30)
    ( 136.00 30.00 179.00) TO ( 5.00 14.00 30.30)
    ( 134.00 33.00 179.00) TO ( 9.00 9.00 30.30)
    ( 126.00 23.00 179.00) TO ( 15.00 1.00 30.30)
  --ABSOLUTE COORDINATES--
  37.) WINDOW-LOWER LEFT
    ( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
    ( 131.00 13.00 164.00) TO ( 12.00 11.00 43.30)
    ( 140.00 13.00 167.00) TO ( 3.00 11.00 46.30)
    ( 152.00 13.00 180.00) TO ( 8.20 11.00 47.30)
    ( 152.00 27.00 187.00) TO ( 8.20 11.00 47.30)
    ( 152.00 36.10 184.00) TO ( 8.20 12.10 43.30)
    ( 152.00 40.30 179.00) TO ( 8.20 16.30 30.30)
    ( 136.00 30.00 179.00) TO ( 5.00 14.00 30.30)
    ( 134.00 33.00 179.00) TO ( 9.00 9.00 30.30)
    ( 126.00 23.00 179.00) TO ( 15.00 1.00 30.30)
  --ABSOLUTE COORDINATES--
  37.) WINDOW-LOWER RIGHT
    ( 126.00 13.00 179.00) TO ( 17.00 11.00 30.30)
    ( 131.00 13.00 164.00) TO ( 12.00 11.00 43.30)
    ( 140.00 13.00 167.00) TO ( 3.00 11.00 46.30)
    ( 152.00 13.00 180.00) TO ( 8.20 11.00 47.30)
    ( 152.00 27.00 187.00) TO ( 8.20 11.00 47.30)
    ( 152.00 36.10 184.00) TO ( 8.20 12.10 43.30)
    ( 152.00 40.30 179.00) TO ( 8.20 16.30 30.30)
    ( 136.00 30.00 179.00) TO ( 5.00 14.00 30.30)
    ( 134.00 33.00 179.00) TO ( 9.00 9.00 30.30)
    ( 126.00 23.00 179.00) TO ( 15.00 1.00 30.30)
  --ABSOLUTE COORDINATES--

```

Figure 11. Subroutine VISVDM Output.

```

58.) WINDOW-FRONT RIGHT
  9 VERTICES --INPUT COORDINATES--
    ( 134.00 -33.00 179.00) TO ( 9.60 57.00 39.30)
    ( 128.00 -23.00 179.00) TO ( 15.60 47.00 38.30)
    --ABSOLUTE COORDINATES--
    ( 126.00 13.00 178.00) TO ( 17.00 11.00 37.30)
    ( 127.00 20.00 178.00) TO ( 16.60 4.00 37.30)
    ( 129.70 29.00 178.00) TO ( 14.10 -5.00 37.30)
    ( 135.00 37.00 178.00) TO ( 8.00 13.00 37.30)
    ( 127.60 36.50 159.00) TO ( 16.00 -14.50 18.30)
    ( 118.00 33.30 159.50) TO ( 25.60 -9.30 18.00)
    ( 112.00 26.10 160.00) TO ( 31.60 -2.10 19.30)
    ( 111.00 22.30 161.00) TO ( 32.60 1.70 20.30)
    ( 110.00 13.00 162.00) TO ( 33.60 11.00 21.30)
    --ABSOLUTE COORDINATES--
    ( 126.00 11.00 178.00) TO ( 17.60 13.00 37.30)
    ( 110.00 11.00 162.00) TO ( 33.60 13.00 21.30)
    ( 110.00 -11.00 162.00) TO ( 33.60 35.00 21.30)
    ( 126.00 -11.00 178.00) TO ( 17.60 35.00 37.30)
    --ABSOLUTE COORDINATES--
    ( 126.00 -13.00 178.00) TO ( 17.60 37.00 37.30)
    ( 127.00 -20.00 178.00) TO ( 16.60 44.00 37.30)
    ( 129.70 -29.00 178.00) TO ( 14.10 53.00 37.30)
    ( 135.00 -37.00 178.00) TO ( 8.60 61.00 37.30)
    ( 127.00 -36.50 159.00) TO ( 16.60 62.50 18.30)
    ( 118.00 -33.30 159.50) TO ( 25.60 57.30 18.00)
    ( 112.00 -26.10 160.00) TO ( 31.60 50.10 19.30)
    ( 111.00 -22.30 161.00) TO ( 32.60 46.30 20.30)
    ( 110.00 -13.00 162.00) TO ( 33.60 37.00 21.30)
    --ABSOLUTE COORDINATES--
    ( 86.50 24.70 127.00) TO ( 57.30 -7.70 -13.70)
    ( 87.40 27.00 127.00) TO ( 56.40 -3.60 -13.70)
    ( 90.10 30.00 127.00) TO ( 53.40 -6.00 -13.70)
    ( 92.90 33.00 127.00) TO ( 50.90 -9.60 -13.70)
    ( 99.30 37.60 127.00) TO ( 44.60 -13.60 -13.70)
    ( 111.00 42.00 127.00) TO ( 32.00 -18.00 -13.70)
    ( 106.00 41.20 119.60) TO ( 35.00 -17.20 -21.10)
    ( 105.10 39.50 118.70) TO ( 38.70 -14.50 -30.00)
    ( 103.30 35.00 106.30) TO ( 40.50 -11.00 34.40)
    ( 101.00 28.30 102.90) TO ( 42.00 4.30 37.00)
    ( 101.50 21.60 102.10) TO ( 42.30 2.20 -38.60)
    ( 93.20 21.00 108.60) TO ( 58.60 2.20 -32.10)
    ( 88.60 21.60 115.30) TO ( 35.20 2.20 -25.40)
    ( 86.50 23.40 122.00) TO ( 37.30 6.00 -18.70)
    --ABSOLUTE COORDINATES--
    ( 86.50 -24.70 127.00) TO ( 37.30 48.70 -13.70)
    ( 87.40 -27.00 127.00) TO ( 36.40 41.00 -13.70)
    ( 90.10 -30.00 127.00) TO ( 33.40 54.00 -13.70)
    ( 92.90 -33.00 127.00) TO ( 50.90 57.00 -13.70)
    ( 99.30 -37.60 127.00) TO ( 44.30 51.60 13.70)
    ( 111.00 42.00 127.00) TO ( 32.00 65.00 13.70)
    ( 106.00 -41.20 119.60) TO ( 35.00 65.20 -21.10)

```

Figure 11. Subroutine VISVDM Output.

```

11 ) REFUELING CONTROL      ( 105.10 -38.50 110.70) TO ( 38.70 62.50 -30.00)
( 103.30 35.00 106.30) TO ( 40.50 59.00 -34.40)
( 101.80 -26.30 102.90) TO ( 42.00 52.30 -37.80)
( 101.50 -21.80 102.10) TO ( 42.30 45.60 -38.60)
( 93.20 -21.80 100.60) TO ( 50.60 45.60 -32.10)
( 86.60 -21.80 115.30) TO ( 55.20 45.60 -25.40)
( 86.50 -23.40 122.00) TO ( 57.30 47.40 18.70)
1 VERTICES --INPUT COORDINATES--
( 137.50 -6.00 139.50) TO ( 6.30 30.00 -1.20)
1 VERTICES --INPUT COORDINATES--
( 124.50 5.00 143.00) TO ( 19.30 19.00 2.30)
1 VERTICES --INPUT COORDINATES--
( 124.00 7.50 143.25) TO ( 19.80 16.50 2.55)
1 VERTICES --INPUT COORDINATES--
( 135.00 4.00 140.00) TO ( 8.00 20.00 -.70)
1 VERTICES --INPUT COORDINATES--
( 150.00 6.00 162.00) TO ( 6.20 18.00 41.30)
1 VERTICES --INPUT COORDINATES--
( 142.00 8.00 160.00) TO ( 1.00 24.00 39.30)
1 VERTICES --INPUT COORDINATES--
( 128.00 -5.00 177.00) TO ( 15.00 29.00 36.30)
1 VERTICES --INPUT COORDINATES
( 128.00 5.00 177.00) TO ( 15.00 19.00 36.30)
1 VERTICES --INPUT COORDINATES
( 116.00 18.00 158.00) TO ( 27.00 6.00 17.30)
1 VERTICES --INPUT COORDINATES--
( 116.00 6.00 161.00) TO ( 27.00 26.00 20.30)
1 VERTICES --INPUT COORDINATES
( 116.00 -18.00 158.00) TO ( 27.00 42.00 17.30)
VIS34I CH-53 WITH 12 BOUNDARIES AND 11 MISCELLANEOUS EQUIPMENTS HAS BEEN ADDED.

```

Figure 11. Subroutine VISVDM Output.

The remaining VISVDM printed output includes, for each boundary and miscellaneous equipment, the sequence number, the number of vertices, and the coordinates of each vertex both before and after translation. The last line starting with VIS534I is a message which indicates that VISVDM has successfully completed processing the visibility member.

#### 4.3 EYE POSITIONAL DATA

The eye positional data consist of an (X, Y, Z) coordinate triplet that describes the eye location with respect to the origin of the visibility member data, and the line-of-sight information in the form of a target point for the head (X, Y, Z) or the vertical and horizontal angular offsets for the head (HANG, VANG)\*.

The eye location is entered in the following format (see Figure 12a):

- columns 1-10 the X-coordinate of the eye,
- columns 11-20 the Y-coordinate of the eye,
- columns 21-30 the Z-coordinate of the eye.

This should be entered in the SRP system (i.e. (0,0,0)=seat reference point, and axes FLU). Note that if a decimal point is not punched in the field, it is assumed to be between the second and third to the last columns in each field. Thus, the input card of Figure 12b gives the eye location X=6.12, Y=0.00, Z=31.45 for the plot of Figure 4.

To enter target data (point at which the head is pointing), enter an (X, Y, Z) coordinate triplet as follows (see Figure 13a):

- columns 1-10 X-coordinate of head target (F10.2)
- columns 11-20 Y-coordinate of head target (F10.2)
- columns 21-30 Z-coordinate of head target (F10.2).

This should be entered in the user's coordinate system. Figure 13b shows input for the point X=16.12, Y=0.0, and Z=21.45. The user may use any desired values). Horizontal and vertical offsets to line-of-sight are entered as follows

\*Note that the head position is specified by entering either target data or angular offsets, but not both.







(see Figure 14a):

- columns 1-7 the vertical angle (HANG) offset
- columns 8-14 the horizontal angle (VANG) offset.

Figure 14b shows the sample input for  $HANG=0.0^\circ$  and  $VANG=-45.0^\circ$ . Note that as with the other eye positional input, when no decimal point is entered, the assumed point is between the second and third to the last card columns in each field.

The user can specify the head position by entering either target data or angular offsets, but not both. Which one the user enters depends on the value of TARG in the CNTRL namelist (see Paragraph 4.1).



## SECTION 5

### JOB CONTROL

VISANS originated as a function of the COMputerized BIO-mechanical MAN-model interactive graphics program. The current version of VISANS creates offline plots on a CALCOMP 1036 three-pen plotter using a CDC CYBER computer at Wright-Patterson Air Force Base, Ohio. The job control cards used for these runs are shown in the deck setup of Figure 15. Plot information is transferred to TAPE7 under system control. This plot tape produces three-color plots on a CALCOMP 1036 drum plotter utilizing a CALCOMP Model 925 controller with a universal tape drive.

If online plots are desired, a dummy subrouting, NEWPEN(I) must be added to the Program Source as shown in Figure 16. The deck setup for online plot runs is shown in Figure 17.

The Visibility Analysis program (VISANS) is written in FORTRAN IV using a CALCOMP based plotting package. It uses the following units for I/O:

- Unit 3 - user input, card image format (see Section 4)
- Unit 6 - printed output
- Unit 7 - Gould plotter output
- Unit 9 - Scratch file used by the program.

```

VIS,T25,IØ50,CM105000.  ID#
FTN.
ATTACH,CCPLØT,CCPLØT1036,ID=LIBRARY,SN=ASD.
LABEL,TAPE7,W,D=PE,VSN=Tape#,RING.
LDSET,LIB=CCPLØT.
LGØ.
7/8/9 (EØF)
.
.      Source Deck
.
7/8/9 (EØF)
.
.      Input Data
.
6/7/8/9 (EØJ)

```

Figure 15. Deck Layout for Offline Plot Runs.

```
SUBROUTINE NEWPEN(I)  
RETURN  
END
```

Figure 16. Dummy Subroutine NEWPEN.

VIS,T25,IØ50,CM105000. ID#  
 FTN.  
 ATTACH,CCPLØT,CCPLØT56X,ID=LIBRARY,SN=ASD.  
 LIBRARY,CCPLØT.  
 LGØ.  
 RØUTE,PLØT,TID=Terminal ID,DC=PT,ST=System designation.  
 7/8/9 (EØF)  
 .  
 . Source Deck  
 .  
 7/8/9 (EØF)  
 .  
 . Input Data  
 .  
 6/7/8/9 (EØJ)

Figure 17. Deck Layout for Online Plot Run.



APPENDIX A  
COMPUTATION OF THE VISION ANGLES

As mentioned in Section 1, crew stations are defined geometrically as panels and contours. These panels and contours are represented by closed polygons, and are input to the program in a user defined coordinate system.

Before calculating the vision angles the user defined coordinate system is transformed through the following steps:

- (1) Convert to the three dimensional coordinate system with

+x = forward

+y = left

+z = up

and seat reference point = (0,0,0).

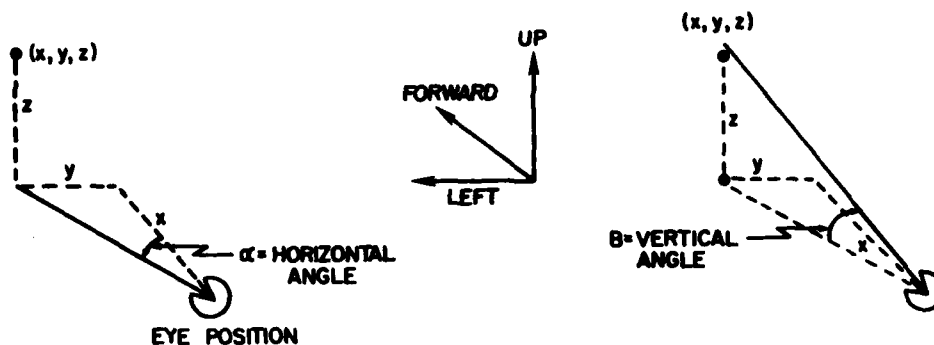
- (2) Translate the origin to the eye location of the crew-member.
- (3) Then, if the crewmembers head is pointed HANG degrees left of forward and VANG degrees above horizontal
  - a) rotate HANG degrees left about the z-axis and
  - b) rotate VANG degrees up about the y-axis.

Angles are calculated in this resulting coordinate system as follows:

If the coordinates of the point are (x, y, z), then

horizontal angle  $\alpha = \tan^{-1}(y/x)$

vertical angle  $\beta = \sin^{-1}(z/\sqrt{x^2+y^2+z^2})$



For the program's visibility plot, these angles are sampled at one inch intervals along the polygon perimeters. To save plotting time and storage, each polygon side is tested to see if it is perpendicular to the x-y plane; and if true, the segment is not sampled (because it will show up as a straight line on the plot). For the printed output the angles are calculated only at the polygon vertices.

APPENDIX B  
VISIBILITY ANALYSIS PROGRAM LISTINGS

```

1  PROGRAM VISANS (INPUT,OUTPUT,TAPES=INPUT,TAPES=OUTPUT,TAPE7,TAPE9) 000100
C * * * * * 000110
C * CBHVIS -- GENERATES VISIBILITY PLOTS USING THREE DIMENSIONAL 000120
C * EYE POSITION, AND CREWSTATION COORDINATES 000130
C * * * * * 000140
C * * * * * 000150
C * THE INPUT STREAM IS AS FOLLOWS: 000160
C * 1. THE NAMELIST CNTRL 000170
C * 2. IF MEN=1; CREWSTATION DATA(SEE SECTION 3 OF USER'S GUIDE) 000180
C * 3. IF EYELOC.NE.0; THE EYE POSITION (5X,3F10.2) 000190
C * 4. IF TARG=1; THREE DIMENSIONAL COORDINATES OF A POINT AT 000200
C * * * * * 000210
C * IF TARG=0; WHICH THE EYE IS LOOKING. (3F10.2) 000220
C * IF TARG=0; THE VERTICAL AND HORIZONTAL LINE OF SIGHT 000230
C * ANGLES(IN THAT ORDER) FOR THE EYES(2F7.2) 000240
C * 5. AS MANY MORE COPIES OF #S 1-4 AS NEEDED 000250
C * 6. THE NAMELIST CNTRL WITH IEND=1 000260
C * * * * * 000270
C * * * * * 000280
C * THE NAMELIST CNTRL'S VARIABLES: 000290
C * MEN.....IF MEN=1 READ IN VISIBILITY DATA FROM UNIT 3 000300
C * THE DATA IS REFORMATTED AND WRITTEN TO UNIT 9 000310
C * FOR USE BY THE PROGRAM. 000320
C * IF MEN=0 THE PROGRAM ASSUMES DATA IS ALREADY PRESENT ON 000330
C * UNIT 9 IN THE PROPER FORMAT AND BYPASSES THE 000340
C * CALL TO VISVDM. THIS IS THE CASE AFTER THE 000350
C * FIRST PLOT WHEN MORE THAN ONE PLOT IS BEING MADE 000360
C * OF A PARTICULAR CREWSTATION. (DEFAULT=0) 000370
C * TARG.....IF TARG=1 ENTER AN (X,Y,Z) COORDINATE TRIPLET OF THE 000380
C * POINT AT WHICH THE EYE IS LOOKING. 000390
C * IF TARG=0 ENTER THE VERTICAL AND HORIZONTAL OFFSETS FOR 000400
C * THE LINE OF SIGHT OF THE EYE, IN DEGREES, 000410
C * WITH RESPECT TO STRAIGHT AHEAD. (DEFTARG=0) 000420
C * IEND IEND=1 SIGNALS THE END OF THE DATA. (DEFAULT=0) 000430
C * EYELOC..EYELOC=0 USE THE X, Y, AND Z COORDINATES OF THE EYE 000440
C * FROM THE PREVIOUS PLOT, IF THIS IS NOT THE FIRST PLOT, 000450
C * OR (0.0, 0.0, 0.0) IF IT IS THE FIRST PLOT 000460
C * EYELOC=1 READ THE EYE COORDINATES FOR THIS PLOT. 000470
C * (DEF: EYELOC=1) 000480
C * ILM.....IF ILM=0 NO VISUAL FIELD LIMITS ARE PLOTTED 000490
C * IF ILM=1 VISUAL FIELD LIMITS ARE PLOTTED (DEF:ILM=1) 000500
C * * * * * 000510
C * * * * * 000520
C * * * * * 000530
C * * * * * 000540
C * * * * * 000550
C * * * * * 000560
C * * * * * 000570
C * * * * * 000580
C * * * * * 000590
C * * * * * 000600
C * * * * * 000610
C * * * * * 000620
C * * * * * 000630
C * * * * * 000640
C * * * * * 000650
C * * * * * 000660
C * * * * * 000670
C * * * * * 000680
C * * * * * 000690
C * * * * * 000700
C * * * * * 000710
C * * * * * 000720
C * * * * * 000730
C * * * * * 000740
C * * * * * 000750
C * * * * * 000760
C * * * * * 000770
C * * * * * 000780
C * * * * * 000790
C * * * * * 000800
C * * * * * 000810
C * * * * * 000820
C * * * * * 000830
C * * * * * 000840
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C * * * * * 000870
C * * * * * 000880
C * * * * * 000890
C * * * * * 000900
C * * * * * 000910
C * * * * * 000920
C * * * * * 000930
C * * * * * 000940
C * * * * * 000950
C * * * * * 000960
C * * * * * 000970
C * * * * * 000980
C * * * * * 000990
C * * * * * 001000

```



```

115 C *****
116 C * ENTER LINE OF SIGHT ANGLES *
117 C * + VANG UP *
118 C * + VANG TO LEFT *
119 C *****
120 READ(3,1005)HANG,VANG
121 17 CONTINUE
122 C *****
123 C * READ IN CANOPY COORD IN SRP SYSTEM *
124 IF(EOF(9).GT.0) GO TO 995
125 NNN=NBND5+NEQPTS
126 CALL VISDPG(0)
127 IF(HANG.LT.0.) IMA=HANG+.5
128 IMA=VANG+.5
129 IF(VANG.LT.0.) IVA=VANG+.5
130 WRITE(6,2005) IMA,DATE,XLEVE,YLEVE,ZLEVE,IMA,IVA
131 CALL VISDPG(5)
132 KBN=3
133 DO 430 IJ=1,NNN
134 READ(9,1004) SNC,NAME,NOVC,((CACXYZ(L,J),L=1,3),J=1,NOVC)
135 IF(EOF(9).GT.0) GO TO 996
136 IF(IJ.LE.NBND5) GO TO 50
137 DO 40 II=1,6
138 40 LNAME(IJ-NBND5,II)=NAME(II)
139 50 CONTINUE
140 C *****
141 C * TRANSLATE COORD. FROM SRP SYSTEM TO LEVE SYSTEM *
142 C *****
143 DO 100 I=1,NOVC
144 LXYZ(1,I)=ACXYZ(1,I)-XLEVE
145 EXYZ(2,I)=ACXYZ(2,I)-YLEVE
146 EXYZ(3,I)=ACXYZ(3,I)-ZLEVE
147 100 CONTINUE
148 C *****
149 C * ROTATE AXES *
150 C *****
151 CALL ROTATE(CXYZ,NOVC,HANG,VANG)
152 C *****
153 C * LOOP THRU XYZ ARRAY AND LOCATE POINTS OF INTERSECTION *
154 C *****
155 NPNTS=0
156 DO 300 I=1,NOVC
157 IVA=-I+1
158 IF(I.EQ.NOVC) IVA=1
159 DELX=EXYZ(1,IVAR)-EXYZ(1,I)
160 DELY=EXYZ(2,IVAR)-EXYZ(2,I)
161 DELZ=EXYZ(3,IVAR)-EXYZ(3,I)
162 VMAG=SQRT(DELX**2+DELY**2+DELZ**2)
163 LIM=IFX(VMAG)+1
164 C *****
165 C * VERTICAL LINE TEST *
166 C *****
167 IF(VMAG.GT.1.4NU.(VMAG-ABS(DELZ)).LE.2.) LIM=2
168 IF(VMAG.EQ.0.) VMAG=1.
169 DO 250 ICHT=1,LIM

```

```

175 D1NCR=(ICNT-1)/VMAG
    IF(ICNT EQ LIM) D1NCR=1.0
    X3=XYZ(1,I)+D1NCR*DELX
    Y3=-(XYZ(2,I)+D1NCR*DELY)
    Z3=XYZ(3,I)+D1NCR*DELZ
    TEMP=0.
    RTMP=X3**2+Y3**2
    IF(RTMP.GT..00001) TEMP=(ATAN2(Y3,X3))*RADANG
    ALPHA=TEMP*180.
    NPNTS=NPNTS+1
    ALPH(NPNTS)=ALPHA
    DEN=SQRT(X3**2+Y3**2+Z3**2)
    C FLAG POINTS THAT LAND ON EYE
    185 IF(TEMP.GT.0.) GO TO 244
        ALPHA=1.E9
        BETAT=1.E9
        ALPH(NPNTS)=ALPHA
        BETA(NPNTS)=BETAT
        GO TO 246
    C VERTICAL ANGLE CALCULATED USING ARCSIN
    190 244 CONTINUE
        BETA=(ASIN(Z3/DEN))*RADANG*90.
        BETA(NPNTS)=BETAT
        GO TO 246
    C
    195 246 CONTINUE
        IF(ICNT.GT.1) GO TO 250
        HERA(I)=(180.-ALPHA)*SIGN(.5,180.-ALPHA)
        VERA(I)=(BETAT-90.)*SIGN(.5,BETAT-90.)
        200 250 CONTINUE
        300 CONTINUE
        C *****
        C IF(IJ.EQ.1) CALL VISPLT
        C *
        C PLOT POINTS ALONG CONTOUR
        C *****
        205 CALL NEMPEN(1)
            IPEN=3
            DO 300 I=1,NPNTS
                XT=ALPH(I)*.04
                YT=BETA(I)*.04
                IF(I.EQ.1) GO TO 373
                ALPH=ABS(ALPH(I)-ALPH(I-1))
                ALPHI=(ALPH(I)+ALPH(I-1))/2
                BBETAI=(BETA(I)+BETA(I-1))/2
                IF(ALPHI.GE.35) IPEN=3
                IF(ALPHI.LT.1. .OR. AA*PHI.GT. 359. .OR.
                    * JBETA1.LT.1. .OR. BB*ETA1.GT. 179.) IPEN=3
                313 IF(IJ GT NBND) RBN=RBN+1
                IF(XD.LT.0..OR.XD.GT.14.3.DP.YD.LT.0..OR.YD.GT.17.125) GO TO 379
                IF(XD.LT.2.0.DP.XD.GT.12.3) AND(YD.GT.5.925) GO TO 379
                IF(IJ.LE.NBND) GO TO 375
                CALL NUMBER(XD,YD,.150,RBN,0.0,-1)
                GO TO 380
                315 CALL PLCT(XD,YI,IPEN)
                    IPEN=2
                    GO TO 380
                373 IPEN=3
                380 CONTINUE
            C *****

```

```

230 C * PRINT TABULAR DATA
C *****
DO 420 I=1,NOVC
  XYZ(I,I)=ACXYZ(IX,I)*IX+XC
  XYZ(I,I)=ACXYZ(IY,I)*IY+YC
  XYZ(I,I)=ACXYZ(IZ,I)*IZ+ZC
420 CONTINUE
  IP= NOVC+7
  CALL VISDPG(IP)
  IF(IILN.NE.0) GO TO 402
  CALL VISDPG(5)
  WRITE(6,2005) INAME,DATE,XLEYE,YLEYE,ZLEYE,IHA,IVA
  DO 450 I=1,NOVC
    WRITE(6,2006) HERA(I),VERA(I),(8XYZ(J,I),J=1,3)
450 CONTINUE
460 CONTINUE
  REWIND 9
  CALL PLOT(14.4,0.0,-3)
  IF(NEQPTS.NE.0) CALL LSLGND(NEQPTS,LNAME)
  TSP=3.
  IF(NEQPTS.EQ.0) ISP=1.
  CALL PLOT(TSP,9.0,3)
  CALL PLOT(TSP,-1.6,-2)
  GO TO 10

255 C
465 CONTINUE
  WRITE (6,2012)
  GO TO 997
995 WRITE (6,2010)
  GO TO 997
996 WRITE (6,2011)
997 CALL PLOTE(AAA)
  STOP

265 C ***** FORMATS
C *****
1001 FORMAT(///,10X,44H INVALID DATA . TARGET LOCATION EQUIVALENT ,
  # 16H TO EYE LOCATION )
1002 FORMAT(3F10.2)
1003 FORMAT(5X,2A4,1X,12,3F6.2,3(1X,A1),3(1X,A2))
1004 FORMAT(13,6A4,13/,4(3F6.2))
1005 FORMAT(2F7.2)
2005 FORMAT(//,38X,23HVISIBILITY PLOT DATA FOR: ,A4,
  # 29HVEY LOCATION IN SRP SYSTEM ( ,2(F6.2,1H),F6.2,1H),
  # //39X,24HLINE-OF-SIGHT IN DEGREES,6X,1H( ,14,2H ,14,1H))
2006 FORMAT(13X,15,3X,15,11X,3F10.3)
2007 //39X,24HLINE-OF-SIGHT IN DEGREES,13X,20HORIGINAL COORDINATES ,
  # 13X,14HMOKIZ. VERT ,16X,A2,8X,A2,6X,A2//
2008 //13X,20HLINE-OF-SIGHT ANGLES,13X,20HORIGINAL COORDINATES ,
  # 13X,14HMOKIZ. VERT ,16X,A2,8X,A2,6X,A2//
2010 FORMAT(53H VIS0504 NO VISIBILITY PLOT DATA AVAILABLE ON UNIT 9. )
2011 FORMAT(131H VIS0514 END OF DATA ON UNIT 9. )
2012 FORMAT(44H VIS0521 VISIBILITY PLOT GENERATED SUCCESSFULLY. )
  END

```



## SYMBOLIC REFERENCE MAP (R=3)

ENTRY POINTS OFF LINE REFERENCES  
10273 VISANS 1

VARIABLES SN TYPE RELOCATION

26370 A	REAL	ARRAY	102	103	104	3*106	3*110	2*111
11553 AAA	REAL		51	100	101	102	103	104
11554 AALPH	REAL		261	211				
11555 AALPH1	REAL		214	212				
12324 ACXYZ	REAL	ARRAY	2*215	147	148	232	233	234
12111 ALPH	REAL	ARRAY	136	2*211	2*212	DEFINED	182	188
11540 ALPHA	REAL		50	2*197	DEFINED	180	186	
11550 BETA1	REAL		182	213				
20404 BETA	REAL	ARRAY	2*215	209	DEFINED	189	194	193
11542 BETAT	REAL		189	2*213	DEFINED	187	193	
11573 BNO	INTEGER		53	2*198	DEFINED			
25274 SXYZ	REAL	ARRAY	51	136	232	233	234	
2 DATE	REAL	ARRAY	45	243	240			
11525 DELX	REAL		164	DEFINED	161			
11526 DELY	REAL		164	DEFINED	162			
11527 DELZ	REAL		164	DEFINED	163			
11541 DEN	REAL		185	DEFINED	183			
11533 DIMGR	REAL		174	DEFINED	175	172	173	175
12-20 SXYZ	REAL	APRAY	50	2*151	2*162	2*163	174	
11-7 EYELOC	INTEGER		54	147	148	69	112	
1 HANG	REAL	VSPT	46	89	DEFINED			
2-17 MEPA	INTEGER		120	2*129	153			
11522 I	INTEGER	ARRAY	52	DEFINED	197	160	161	162
	INTEGER		2*146	2*148	159	198	208	209
			174	176	197	2*234	3*243	
11532 ICNT	INTEGER		2*211	2*213	2*232	2*233		
11511 IFND	INTEGER		145	207	231	262		
11512 IHA	INTEGER		172	196	DEFINED	171		
11521 II	INTEGER		55	DEFINED	72	129		
11515 IJ	INTEGER		132	DEFINED	128			
	INTEGER		2*140	139		220		
			138	201	217			
0 ILI4	INTEGER		135	DEFINED				
1 ILN	INTEGER	VSPT	46	DEFINED	71			
2 INAME	INTEGER	VISADC	45	238				
11511 IP	INTEGER	AKPAY	46	132	DEFINED	124		
11543 IPEN	INTEGER		237	240				
0 IPG	INTEGER		223	DEFINED	214	215	224	226
11513 IVA	INTEGER		45	206				
11524 IVAR	INTEGER		132	DEFINED	130	131	160	
11506 IX	INTEGER		161	163	DEFINED	159		
0 IX1	INTEGER		241	124				
1 IX2	INTEGER	AXES	48	99				
2 IY1	INTEGER	AXES	48	232				
3 IY2	INTEGER	AXES	48	233				

RELOCATION

VARIABLES SN TYPE

11510 IZ INTEGER

11511 IZ1 INTEGER

11512 IZ2 INTEGER

11513 J INTEGER

11514 L INTEGER

11515 L1M INTEGER

11516 LNA4E INTEGER

11517 MHX REAL

11518 MHY REAL

11519 MHZ REAL

11520 NAME INTEGER

11521 NAME INTEGER

11522 NAME INTEGER

11523 NAME INTEGER

11524 NAME INTEGER

11525 NAME INTEGER

11526 NAME INTEGER

11527 NAME INTEGER

11528 NAME INTEGER

11529 NAME INTEGER

11530 NAME INTEGER

11531 NAME INTEGER

11532 NAME INTEGER

11533 NAME INTEGER

11534 NAME INTEGER

11535 NAME INTEGER

11536 NAME INTEGER

11537 NAME INTEGER

11538 NAME INTEGER

11539 NAME INTEGER

11540 NAME INTEGER

11541 NAME INTEGER

11542 NAME INTEGER

11543 NAME INTEGER

11544 NAME INTEGER

11545 NAME INTEGER

11546 NAME INTEGER

11547 NAME INTEGER

11548 NAME INTEGER

11549 NAME INTEGER

11550 NAME INTEGER

11551 NAME INTEGER

11552 NAME INTEGER

11553 NAME INTEGER

11554 NAME INTEGER

11555 NAME INTEGER

11556 NAME INTEGER

11557 NAME INTEGER

11558 NAME INTEGER

11559 NAME INTEGER

11560 NAME INTEGER

11561 NAME INTEGER

11562 NAME INTEGER

11563 NAME INTEGER

11564 NAME INTEGER

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51

EXTERNALS

EDF	TYPE	ARGS	REFERENCES
LSLGN0	REAL	1	137
NUMPER		2	125
PLOT		1	248
PLOTS		6	205
ROTATE		3	221
SRRT		1	62
VISDPC		1	261
VISPLT		3	61
VISDPC		4	153
VISDPC	REAL	1 LIBRARY	164
VISDPC		1	110
VISDPC		0	127
VISDPC		0	201
VISDPC		0	65
VISDPC		0	61

INLINE FUNCTIONS

ABS	TYPE	ARGS	DEF LINE	REFERENCES
ABS	REAL	1	INTRIN	211
IFIX	INTEGER	1	INTRIN	159
SIGN	REAL	2	INTRIN	165
				197
				198

MANEGLISTS

DEF LINE	REFERENCES
50	75
	76

STATEMENT LABELS

DEF LINE	REFERENCES
10332 5	91
10332 7	110
10332 10	67
10332 15	114
10332 17	121
10332 40	140
10332 50	141
10332 100	149
10332 244	192
10332 246	195
10332 250	199
10332 300	200
10332 373	217
10332 375	223
10332 379	226
10332 380	227
10332 402	241
10332 420	235
10332 450	244
10332 450	247
10332 450	255
10332 450	258
10332 450	260
10332 450	261
10332 450	264
10332 450	268
10332 450	269
10332 450	270
10332 450	271
10332 450	272
10332 450	275
10332 450	276
10332 450	279
10332 450	280

STATEMENT LABELS  
11416 2012 FMT  
DEF LINE REFERENCES  
281 256

LOOPS	LABEL	INDEX	FROM TO	LENGTH	PROPERTIES	EXT REFS	EXITS	NOT INNER
10-34	400	IJ	135 245	345B				
10450	40	IJ	139 140	38	INSTACK			
10470	100	I	145 149	68	INSTACK			
10503	300	I	158 200	127B				
10537	250	ICNT	171 199	118				
10641	360	I	207 227	61B				
10736	420	I	231 235	11B	OPT			
10763	450	I	242 244	14B				

COMMON BLOCKS LFNTH

VISAOC	VSPT	AXES	MEMBERS	BIAS NAME (LENGTH)	1 ILN	1 HANG	4 YLEVE	8 NEOPTS	1 IX2	4 IZ1	2 DATE	2 VANG	5 ZLEVE	2 IY1	5 IZ2
			0 IPS	(1)	(1)	(1)	(1)	(1)	(1)	(1)	(2)	(1)	(1)	(1)	(1)
			0 ILIM	(1)											
			3 XLEVE	(1)											
			6 INAME	(2)											
			0 IX1	(1)											
			3 IY2	(1)											
			6 SEAT	(3)											

STATISTICS

PROGRAM LENGTH	165378	7531
BUFFER LENGTH	76728	4026
CM LABELED COMMON LENGTH	268	22
320008 CM USED		

```

1      SUBROUTINE VISPLT
      COMMON /VISAD/ IPIG,ILN,DATE(2)
      COMMON /VISPT/ ILIH,HANG,VANG,XLEYE,YLEYE,ZLEYE,
      & INAL(2),NEOPTS
      DIMENSION AB(3,4)
      INTEGER ABC(4)
      DIMENSION INT(3),IHL(3),IVT(3),IVL(3)
      DATA INT/9,RIGHT OF ,5MFOM ,ARLEFT OF ,IHL/9,5,8/
      DATA IVT/6,BELOW ,SHFROM ,6HABOVE ,IVL/6,5,6/
      DATA AB/165,66,-82,95,66,-82,74,48,-56,56,48 , 66./
      DATA ABC/1HM,1HP,1HF,1HS/

      C      CALL PLOT(1,0,-3)
      C *****
      C *      PLOT HEADINGS
      C *****
      AL=17.
      IF(NEOPTS.EQ.0) AL=AL-2.
      CALL SYMBOL(1,2,8,-3,16HVERTICAL DEGREES,90.,16)
      CALL SYMBOL(5,3,3,2,18HFROM LINE-OF-SIGHT,90.,18)
      TSP=(AL-9.5)/2.+6
      CALL SYMBOL(TSP,3,8,-5,19HVISIBILITY ANALYSIS ,0.,19)
      TSP=(AL-4.2)/2.+6
      CALL SYMBOL(TSP,9,4,-2,13HCREWSTATION; ,0.,13)
      CALL SYMBOL(999,999,-2,1NAME(1),0.,4)
      CALL SYMBOL(999,999,-2,1NAME(2),0.,4)
      TSP=(AL-11.1)/2.+6
      CALL SYMBOL(TSP,-4,-3,37HHORIZONTAL DEGREES FROM LINE-OF-SIGHT,
      & 0.,37)
      C *****
      C *      OUTLINE AREA OF PLOT
      C *****
      CALL PLOT(1,2,1,5,3)
      CALL PLOT(1,2,6,8,2)
      CALL PLOT(15,6,8,2)
      CALL PLOT(15,6,1,5,2)
      CALL PLOT(1,1,1,6,2)
      C *****
      C *      DRAW HORIZONTAL GRID
      C *****
      CALL NEMPEN(2)
      XC=15.6
      XD=1.1
      YC=1.6
      DO 320 I=1,17,2
      YC=YC+.4
      CALL PLOT(XD,YC,3)
      CALL PLOT(XC,YC,2)
      IF(I.EQ.17) GO TO 320
      IF(I.EQ.1) XC=13.6
      IF(I.EQ.15) XD=3.2
      YC=YC+.4
      CALL PLOT(XC,YC,3)
      CALL PLOT(XD,YC,2)
      320 CONTINUE
      C *****
      C *      JAW VERTICAL GRID
      C *****

```











STATEMENT LABELS

DEF LINE	REFERENCES
315 318	132
316 339	136
143 340	61
0 345	99
0 350	108
243 353	109
0 360	111
451 362	174
0 363	169
467 364	181
0 365	166

INACTIVE

LOOPS LABEL	INDEX	FROM-TO	LENGTH	PROPERTIES
64 320	I	45 55	308	EXT REFS
117 340	I	61 71	278	EXT REFS
215 350	I	99 108	268	EXT REFS
247 360	I	111 120	278	EXT REFS
402 365	I	166 190	778	EXT REFS
407 363	K	169 189	678	EXT REFS
412 363	J	171 189	628	EXT REFS

COMMON BLOCKS	LENGTH	MEMBERS	BIAS NAME(LENGTH)
VISADC	4	0 IPG	(1)
VSPT	9	0 ILIM	(1)
		3 XLEYE	(1)
		6 INAME	(2)

2 DATE (2)  
2 VANG (1)  
5 ZLEYE (1)

1 ILW (1)  
1 HANG (1)  
4 YLEYE (1)  
8 NEQPTS (1)

STATISTICS

PROGRAM LENGTH	15248	852
CM LABELED COMMON LENGTH	158	13
320008 CM USED		

```

1      SUBROUTINE VISVDM
C *****
C * CBMVDM - VISIBILITY DATABASE MAINTENANCE *
C *
C *****
C      COMMON /VISADC/ IPG,ILN,DATE(12)
C      COMMON /AXES/ IX1,IX2,IY1,IY2,IZ1,IZ2,ACXYZ(3)
C      INTEGER IYIP(6),BNV,NAME(12),ITYPE(6)
C      INTEGER BNO(100),BNAME(6,100)
C      REAL BX(25),BY(25),BZ(25),BXYZ(3,25,100)
C      DATA IADD/4*HADD/
C      DATA IYIP/1NF,1HA,1HL,1HR,1HU,1HD/
C      DATA IYTYPE /1,-1,2,-2,3,-3/,BLANK/4H
C      DATA BXYZ/7100*0./
C      IPG=0
C      JCHK=0
C *****
C * COMMAND PROCESSOR *
C *****
C      10 READ(3,1000) IOPR,NAME,NBND,NEQPTS,ACXYZ,IX,IY,IZ,DATE
C      CALL VISDPG(10)
C      IF(IOPR.EQ.IADD) GO TO 20
C      ** ERROR ** 1ST CARD IS NOT AN 'ADD' CARD
C      WRITE(6,1001) IOPR,NAME,NBND,NEQPTS,ACXYZ,IX,IY,IZ
C      WRITE(6,2000) IOPR
C      GO TO 710
C *****
C * ADD CREW STATION DATA MEMBER *
C *****
C      20 CONTINUE
C      CALL VISDPG(1)
C      PRINT THE 1ST INPUT CARD AS READ IN
C      WRITE(5,1001) IOPR,NAME,NBND,NEQPTS,ACXYZ,IX,IY,IZ
C      IF(NAME(1).NE.BLANK.OR.NAME(2).NE.BLANK) GO TO 22
C      CALL VISDPG(1)
C      WRITE(5,2005) IOPR
C      GO TO 10
C      22 NBN=NBNDS+NEQPTS
C      IF(NBN.GE.1.AND.NBN.LE.100.AND.NEQPTS.LE.0) GO TO 25
C      ** ERROR ** TOTAL NUMBER OF BOUNDARIES AND MISC EQUIP TOO LARGE
C      CALL VISDPG(1)
C      WRITE(6,2007) NAME
C      GO TO 10
C      25 DO 30 I=1,N
C      IF(IX.EQ.IYIP(I)) GO TO 40
C      30 CONTINUE
C      ** ERROR ** ILLEGAL X-AXIS QUALIFIER
C      CALL VISDPG(1)
C      WRITE(6,2008) IX,NAME
C      GO TO 10
C      40 IX1=IABS(ITYPE(I))
C      IX2=ISIGN(1,ITYPE(I))
C      DO 50 I=1,6
C      IF(IY.EQ.IYIP(I)) GO TO 60
C      50 CONTINUE
C      ** ERROR ** ILLEGAL Y-AXIS QUALIFIER
C      CALL VISDPG(1)

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        WRITE(6,2009) IY,NAME
        GO TO 10
    60  IY1=IABS(IYTYPE(I))
        IY2=ISIGN(1,IYTYPE(I))
        DO 70 I=1,6
            IF(IY2.EQ.IYTYPE(I)) GO TO 80
        70  CONTINUE
        C ** ERROR ** ILLEGAL Z-AXIS QUALIFIER
        CALL VISDPG(1)
        WRITE(6,2010) IZ,NAME
        GO TO 10
    80  IZ1=IABS(IYTYPE(I))
        IZ2=ISIGN(1,IYTYPE(I))
        IF(IZ1.NE.IY1.AND.IZ1.NE.IZ1.AND.IY1.NE.IZ1) GO TO 95
        C ** ERROR ** COLINEAR AXES
        CALL VISDPG(1)
        WRITE(6,2011) NAME
        GO TO 10
    95  CONTINUE
        CALL VISDPG(4)
        WRITE(6,2019) NAME,DATE,NBNDOS,NEQPTS,ACXYZ,IX,IY,IZ
        WRITE(6,2012) NAME,NBNDOS,NEQPTS,ACXYZ,IX,IY,IZ
        C PROCESSOR BOUNDARY DEFINED
        DO 110 I=1,NNN
            RFAD(3,1002) BNO(I),(BNAME(J,I),J=1,6),BNV,
            * (BX(J),BY(J),BZ(J),J=1,6)
            K=I-1
            DO 93 J=1,K
                IF(I.NE.1.AND.BNO(J).EQ.BNO(I)) GO TO 94
    93  CONTINUE
            C+ CALL VISDPG(1)
            WRITE(6,2025) (BNAME(L,I),L=1,6),(BNAME(L,J),L=1,6)
            JCHK=JCHK+1
    99  DO 100 J=1,BNV
                XYZ(IX1,J,I)=(BX(J)-ACXYZ(1))*IX2
                XYZ(IY1,J,I)=(BY(J)-ACXYZ(2))*IY2
                XYZ(IZ1,J,I)=(BZ(J)-ACXYZ(3))*IZ2
    100  CALL VISDPG(1)
            WRITE(6,1003) BNO(I),(BNAME(J,I),J=1,6),BNV
            DO 107 J=1,BNV
                CALL VISDPG(1)
    107  WRITE(6,1004) (BX(J),BY(J),BZ(J),(BXZ(K,J,I),K=1,3))
            IF(JCHK.EQ.0) WRITE(6,2013) BNO(I),(BNAME(J,I),J=1,6),BNV,
            * ((XYZ(K,J,I),K=1,3),J=1,BNV)
    110  CONTINUE
            IF(JCHK.NE.0) GO TO 170
        C PROCESSING COMPLETED SUCCESSFULLY
        WRITE(6,2026) NAME,NBNDOS,NEQPTS
        REMIND 9
        RETURN
    170  ERROR ENCOUNTERED DURING PROCFSSING
        WRITE(6,2029) NAME,JCHK
        GO TO 710
    110  C
        C

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110 C END
111 C
112 710 WAIT=(6,2039)
113 STOP
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SYMBOLIC REFERENCE MAP (R=3)

ENTRY POINTS	DEF LINE	REFERENCES	1	108
1 VISVDM	1	108		
VARIABLES	SN	TYPE	RELOCATION	AXES
6 ACX12	REAL	ARRAY	AXES	
345 BLANK	REAL	REFS	95	DEFINED
1177 BNAME	REAL	REFS	2*30	DEFINED
1033 AND	INTEGER	REFS	9	DEFINED
1000 BNV	INTEGER	REFS	9	DEFINED
2327 AX	REAL	REFS	82	DEFINED
242 GXY2	REAL	REFS	10	DEFINED
		REFS	100	DEFINED
		REFS	101	DEFINED
		REFS	14	DEFINED
		REFS	82	DEFINED
		REFS	82	DEFINED
		REFS	2*101	DEFINED
		REFS	93	DEFINED
		REFS	94	DEFINED

VA- 2360 2411 1011	BY BZ I	SN REAL REAL INTEGER	TYPE REAL REAL INTEGER	RELOCATION ARRAY ARRAY ARRAY	OPT=1	74/74	1011	1012	1013	1014	1015	1016	1017	1018	1019	1020	1021	1022	1023	1024	1025	1026	1027	1028	1029	1030	1031	1032	1033	1034	1035	1036	1037	1038	1039	1040	1041	1042	1043	1044	1045	1046	1047	1048	1049	1050	1051	1052	1053	1054	1055	1056	1057	1058	1059	1060	1061	1062	1063	1064	1065	1066	1067	1068	1069	1070	1071	1072	1073	1074	1075	1076	1077	1078	1079	1080	1081	1082	1083	1084	1085	1086	1087	1088	1089	1090	1091	1092	1093	1094	1095	1096	1097	1098	1099	1100	1101	1102	1103	1104	1105	1106	1107	1108	1109	1110	1111	1112	1113	1114	1115	1116	1117	1118	1119	1120	1121	1122	1123	1124	1125	1126	1127	1128	1129	1130	1131	1132	1133	1134	1135	1136	1137	1138	1139	1140	1141	1142	1143	1144	1145	1146	1147	1148	1149	1150	1151	1152	1153	1154	1155	1156	1157	1158	1159	1160	1161	1162	1163	1164	1165	1166	1167	1168	1169	1170	1171	1172	1173	1174	1175	1176	1177	1178	1179	1180	1181	1182	1183	1184	1185	1186	1187	1188	1189	1190	1191	1192	1193	1194	1195	1196	1197	1198	1199	1200	1201	1202	1203	1204	1205	1206	1207	1208	1209	1210	1211	1212	1213	1214	1215	1216	1217	1218	1219	1220	1221	1222	1223	1224	1225	1226	1227	1228	1229	1230	1231	1232	1233	1234	1235	1236	1237	1238	1239	1240	1241	1242	1243	1244	1245	1246	1247	1248	1249	1250	1251	1252	1253	1254	1255	1256	1257	1258	1259	1260	1261	1262	1263	1264	1265	1266	1267	1268	1269	1270	1271	1272	1273	1274	1275	1276	1277	1278	1279	1280	1281	1282	1283	1284	1285	1286	1287	1288	1289	1290	1291	1292	1293	1294	1295	1296	1297	1298	1299	1300	1301	1302	1303	1304	1305	1306	1307	1308	1309	1310	1311	1312	1313	1314	1315	1316	1317	1318	1319	1320	1321	1322	1323	1324	1325	1326	1327	1328	1329	1330	1331	1332	1333	1334	1335	1336	1337	1338	1339	1340	1341	1342	1343	1344	1345	1346	1347	1348	1349	1350	1351	1352	1353	1354	1355	1356	1357	1358	1359	1360	1361	1362	1363	1364	1365	1366	1367	1368	1369	1370	1371	1372	1373	1374	1375	1376	1377	1378	1379	1380	1381	1382	1383	1384	1385	1386	1387	1388	1389	1390	1391	1392	1393	1394	1395	1396	1397	1398	1399	1400	1401	1402	1403	1404	1405	1406	1407	1408	1409	1410	1411	1412	1413	1414	1415	1416	1417	1418	1419	1420	1421	1422	1423	1424	1425	1426	1427	1428	1429	1430	1431	1432	1433	1434	1435	1436	1437	1438	1439	1440	1441	1442	1443	1444	1445	1446	1447	1448	1449	1450	1451	1452	1453	1454	1455	1456	1457	1458	1459	1460	1461	1462	1463	1464	1465	1466	1467	1468	1469	1470	1471	1472	1473	1474	1475	1476	1477	1478	1479	1480	1481	1482	1483	1484	1485	1486	1487	1488	1489	1490	1491	1492	1493	1494	1495	1496	1497	1498	1499	1500	1501	1502	1503	1504	1505	1506	1507	1508	1509	1510	1511	1512	1513	1514	1515	1516	1517	1518	1519	1520	1521	1522	1523	1524	1525	1526	1527	1528	1529	1530	1531	1532	1533	1534	1535	1536	1537	1538	1539	1540	1541	1542	1543	1544	1545	1546	1547	1548	1549	1550	1551	1552	1553	1554	1555	1556	1557	1558	1559	1560	1561	1562	1563	1564	1565	1566	1567	1568	1569	1570	1571	1572	1573	1574	1575	1576	1577	1578	1579	1580	1581	1582	1583	1584	1585	1586	1587	1588	1589	1590	1591	1592	1593	1594	1595	1596	1597	1598	1599	1600	1601	1602	1603	1604	1605	1606	1607	1608	1609	1610	1611	1612	1613	1614	1615	1616	1617	1618	1619	1620	1621	1622	1623	1624	1625	1626	1627	1628	1629	1630	1631	1632	1633	1634	1635	1636	1637	1638	1639	1640	1641	1642	1643	1644	1645	1646	1647	1648	1649	1650	1651	1652	1653	1654	1655	1656	1657	1658	1659	1660	1661	1662	1663	1664	1665	1666	1667	1668	1669	1670	1671	1672	1673	1674	1675	1676	1677	1678	1679	1680	1681	1682	1683	1684	1685	1686	1687	1688	1689	1690	1691	1692	1693	1694	1695	1696	1697	1698	1699	1700	1701	1702	1703	1704	1705	1706	1707	1708	1709	1710	1711	1712	1713	1714	1715	1716	1717	1718	1719	1720	1721	1722	1723	1724	1725	1726	1727	1728	1729	1730	1731	1732	1733	1734	1735	1736	1737	1738	1739	1740	1741	1742	1743	1744	1745	1746	1747	1748	1749	1750	1751	1752	1753	1754	1755	1756	1757	1758	1759	1760	1761	1762	1763	1764	1765	1766	1767	1768	1769	1770	1771	1772	1773	1774	1775	1776	1777	1778	1779	1780	1781	1782	1783	1784	1785	1786	1787	1788	1789	1790	1791	1792	1793	1794	1795	1796	1797	1798	1799	1800	1801	1802	1803	1804	1805	1806	1807	1808	1809	1810	1811	1812	1813	1814	1815	1816	1817	1818	1819	1820	1821	1822	1823	1824	1825	1826	1827	1828	1829	1830	1831	1832	1833	1834	1835	1836	1837	1838	1839	1840	1841	1842	1843	1844	1845	1846	1847	1848	1849	1850	1851	1852	1853	1854	1855	1856	1857	1858	1859	1860	1861	1862	1863	1864	1865	1866	1867	1868	1869	1870	1871	1872	1873	1874	1875	1876	1877	1878	1879	1880	1881	1882	1883	1884	1885	1886	1887	1888	1889	1890	1891	1892	1893	1894	1895	1896	1897	1898	1899	1900	1901	1902	1903	1904	1905	1906	1907	1908	1909	1910	1911	1912	1913	1914	1915	1916	1917	1918	1919	1920	1921	1922	1923	1924	1925	1926	1927	1928	1929	1930	1931	1932	1933	1934	1935	1936	1937	1938	1939	1940	1941	1942	1943	1944	1945	1946	1947	1948	1949	1950	1951	1952	1953	1954	1955	1956	1957	1958	1959	1960	1961	1962	1963	1964	1965	1966	1967	1968	1969	1970	1971	1972	1973	1974	1975	1976	1977	1978	1979	1980	1981	1982	1983	1984	1985	1986	1987	1988	1989	1990	1991	1992	1993	1994	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017	2018	2019	2020	2021	2022	2023	2024	2025	2026	2027	2028	2029	2030	2031	2032	2033	2034	2035	2036	2037	2038	2039	2040	2041	2042	2043	2044	2045	2046	2047	2048	2049	2050	2051	2052	2053	2054	2055	2056	2057	2058	2059	2060	2061	2062	2063	2064	2065	2066	2067	2068	2069	2070	2071	2072	2073	2074	2075	2076	2077	2078	2079	2080	2081	2082	2083	2084	2085	2086	2087	2088	2089	2090	2091	2092	2093	2094	2095	2096	2097	2098	2099	2100	2101	2102	2103	2104	2105	2106	2107	2108	2109	2110	2111	2112	2113	2114	2115	2116	2117	2118	2119	2120	2121	2122	2123	2124	2125	2126	2127	2128	2129	2130	2131	2132	2133	2134	2135	2136	2137	2138	2139	2140	2141	2142	2143	2144	2145	2146	2147	2148	2149	2150	2151	2152	2153	2154	2155	2156	2157	2158	2159	2160	2161	2162	2163	2164	2165	2166	2167	2168	2169	2170	2171	2172	2173	2174	2175	2176	2177	2178	2179	2180	2181	2182	2183	2184	2185	2186	2187	2188	2189	2190	2191	2192	2193	2194	2195	2196	2197	2198	2199	2200	2201	2202	2203	2204	2205	2206	2207	2208	2209	2210
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STATEMENT LABELS

DEF LINE REFERENCES 43

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PAGE 6

08/05/81 15.45.00

FTN 4.8+128

74/74 OPT=1

SUBROUTINE VISDOM

STATISTICS  
PROGRAM LENGTH 21156B 8814  
CM LABELED COMMON LENGTH 158 13  
32000B CM USED





PAGE 2

06/05/81 15.45.00

FTN 4.8+528

74/74 OPT=1

SUBROUTINE VISDPG

STATISTICS

PROGRAM LENGTH	338	27
CM LABELED COMMON LENGTH	48	4
32000 CM USED		



PAGE 2

08/15/81 15.45.00

FTN 4.84528

74/74 OPT=1

SUBROUTINE LSLGND

STATISTICS  
PROGRAM LENGTH 1578 111

52008 CM USED

```

1 SUBROUTINE VISTPG
C *****
C * VISTPG PRINTS A TITLE PAGE
C *****
5 WRITE(6,1000)
WRITE(6,1001)
WRITE(6,1002)
RETURN
C
10 1000 FORMAT (1HS)
1001 FORMAT(23H1 A COMPUTER PROGRAM OF/
132H THE UNITED STATES AIR FORCE/
242H AEROSPACE MEDICAL RESEARCH LABORATORY/
342H WRIGHT-PATTERSON AIR FORCE BASE, OHIO/
415H ...../
556H THE ELECTRICAL & COMPUTER ENGINEERING DIVISION/
649H UNIVERSITY OF DAYTON RESEARCH INSTITUTE/
723H DAYTON , OHIO)
1002 FORMAT ( 15(//),
1 50X,14H-- VISANS -- ,//,40X,30HOREMEMBER VISIBILITY ANALYSIS,
2 6H PROGRAM )
C
20 END

```

SYMBOLIC REFERENCE MAP (R=3)

ENTRY POINTS	DEF LINE	REFERENCES
1 VISTPG	1	6

FILE NAMES	MODE	WRITS	5	6	7
TAPE6	FMT				

STATEMENT LABELS	DEF LINE	REFERENCES
22 1000 FMT	10	F
24 1001 FMT	11	6
65 1002 FMT	19	7

STATISTICS	PROGRAM LENGTH	768	62
	320009 CM USED		



SUBROUTINE COTATE 74/74 OPT=1

VARIABLES SN TYPE  
64 VCOS REAL  
65 VSIN REAL

RELOCATION

REFS  
REFS

22  
23

30  
30

28  
28

EXTERNALS TYPE  
COS REAL  
SIN REAL

ARGS REFERENCES  
1 LIBRARY 11  
1 LIBRARY 12

22  
23

STATEMENT LABELS  
0 100  
0 200

DEF LINE REFERENCES  
20 16  
31 27

LOOPS LABEL INDEX  
23 100 I  
4 200 I

FROM-TO LENGTH PROPERTIES  
16 20 68 INSTACK  
27 31 68 INSTACK

STATISTICS  
PROGRAM LENGTH  
32008 CH USED

1628 114

CSU NOS/3E L530C L530C-CM83 R N 09.21

15.44.28.PMG326K FROM /92

15.44.28.IP 0000012. WORDS - FILE INPUT , DC 04

15.44.28.PMG, I10, I01. L710431 POTTER

15.44.30.ATTACH, FILE, VISPROG, NR=1.

15.44.30.AT CY= 052 SN=AMRL

15.45.00.FTN, I=FILE, R=3.

15.45.58 3.801 CP SECONDS COMPILATION TIME

15.45.58.OP 0001260 WORDS - FILE OUTPUT , DC 40

15.45.58.MS 1.592 WORDS ( 32832 MAX USED)

15.45.58.CPA 3.862 SEC 1.933 ADJ.

15.45.58.I0 13.798 SEC. 7.810 ADJ.

15.45.58.CH 332.336 KMS. 2.703 ADJ.

15.45.58.CRUS 12.447

15.45.58.COST .56

15.45.58.PP 16.060 SEC. DATE 06/05/61

15.45.58.EJ FND OF JOB, 92 L710461.

PMG928K //// END OF LIST ////



#### REFERENCES

Bapu, P. et al., "User's Guide for COMBIMAN Programs. Version 4",  
AFAMRL-TR-80-91 (AD A-097705) January 1981.

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